Geofeasibility scores

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Problem Statement

 For each report, the source associates an area of uncertainty (AOU) of elliptic shape delimiting a 2σ probability area



Problem Statement

- We need to define an optimal geo-feasibility score *g*, to quantify the overlap of two AOU.
- Here are three basic rules to define the function *g*:
- *g* ∈ [0,1]
- If ellipses do not touch, g = 0
- If ellipses totally overlap, g = 1

Problem Statement



- The geo-feasibility score has to be suitable for very elongated ellipses as well as for circles
- Reasonable approximations are possible (e.g. approximating an ellipse to a circle is NOT a reasonable approximation)

Candidate Metrics

• The normalized area of overlap

- The area of overlap is normalized by the area of the smaller ellipse
- Corresponds to human operator intuition.

Candidate Metrics

- Statistical Approaches
- Integrated product of two Gaussian distributions
 Corresponds to Bayes factor.
- Symmetric KL (Kullback-Leibler) divergence
 - Distance between two distributions.
- Generalized Likelihood Ratio (GLR)
 - Find most likely position of a single boat, evaluate the likelihood that it generated the reported distributions.

Challenges

• Closed form analytical calculation of overlap area is not possible

• Numerical methods based on optimization are not fast enough

Proposed solutions

- Newton's method to find intersection points and analytical approximation to the normalized area of the overlap
- Monte-Carlo integration to find the normalized area of overlap
- Generalized Likelihood Ratio gives a fast and meaningful approximation to the operator's intuition

Analytical Method

- 2 steps:
- Find the intersection points
 - -Too hard to find analytically
- Calculate the area
 - -Using integration in polar coordinates

Finding points of Intersection

Using Newton's Method
-In-and-out method for starting points



Calculating area

- 3 cases:
- 0 or 1 points of intersection

-Area is zero or is equal to the area of the smaller ellipse

- 2 or 3 points of intersection
- 4 points of intersection

2 or 3 points of intersection

• Same case considering in-and-out technique



For 2 points

• Using polar coordinates



Area of ellipse's portion – Area of the triangle



Calculation

• Ellipse in polar coordinates (R = radius)

$$R(\theta) = \frac{ab}{\sqrt{a^2 + (b^2 - a^2)\cos^2(\theta)}}$$

Integral

$$\int_{\theta_1}^{\theta_2} \frac{R^2(\theta)}{2} d\theta = \left[\frac{ab}{2} \tan^{-1}\left(\frac{a\tan(\theta)}{b}\right)\right]_{\theta_1}^{\theta_2}$$

Be careful...

• The integral uses inverse tangent function

$$- \theta \in \left(\frac{-\pi}{2}, \frac{\pi}{2}\right)$$

• Too near ellipses center



4 points of intersection

• Extension of the 2 points case



 E_i = Area of ellipse i

$a_i =$	\sum
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Area of intersection = $\frac{E_1 + E_2 - \sum_{i=1}^4 a_i}{2}$

Hard to code

• Approximation by a four sided object



Performance

• The slow part of the program is if the ellipses actually intersect

 for 100,000 pairs of ellipses that intersect about 45% of the time, it takes between 640 and 710 seconds.

• The algorithm computes an estimate of a multidimensional integral

$$I = \iiint_{x,y,z,\dots} f(x,y,z,\dots) dx dy dz \dots$$

• Naïve algorithm draws samples $(x_{i,}y_{i,}z_{i,...})$ uniformly from the integration area and estimates its value as follows

$$\hat{I} = \frac{1}{N} \sum_{i=1}^{N} f(x_i, y_i, z_i,...)$$

 However, in many cases it is beneficial to draw samples from some pdf p(x,y,z,...)

$$I = \iiint_{x,y,z,\dots} \frac{f(x,y,z,\dots)}{p(x,y,z,\dots)} p(x,y,z,\dots) dxdydz\dots$$

And use the so called importance sampling

$$\hat{I} = \frac{1}{N} \sum_{i=1}^{N} \frac{f(x_i, y_i, z_i, ...)}{p(x_i, y_i, z_i, ...)}$$

• Normalized intersection area of two ellipses defined by the regions S_1 and S_2

$$g_a = \frac{\int \mathbf{1}_{\mathbf{x} \in S_1 \cap S_2} d\mathbf{x}}{\int \mathbf{1}_{\mathbf{x} \in \min(S_1, S_2)} d\mathbf{x}}$$

 Can be estimated using Monte Carlo with importance sampling



 Integrated product of two Gaussian distributions

$$g_p = \int_{\mathbf{x}} p_1(\mathbf{x} | \Theta_1) p_2(\mathbf{x} | \Theta_2) d\mathbf{x}$$

• Can be estimated using Monte Carlo even without importance sampling

$$\hat{g}_{p} = \frac{1}{N} \sum_{i=1}^{N/2} p_{1}(\mathbf{x}_{i}^{2} | \Theta_{1}) + \frac{1}{N} \sum_{i=1}^{N/2} p_{2}(\mathbf{x}_{i}^{1} | \Theta_{2})$$

 We assume that a source provides us with measurements of target positions and Maximum Likelihood (ML) estimators of covariance matrices

$$y_1, \hat{R}_1, y_2, \hat{R}_2$$

• And we choose to construct a test statistic to discriminate between the two hypotheses

$$H_1: \quad \mathbf{\mu}_1 = \mathbf{\mu}_2$$
$$H_0: \quad \mathbf{\mu}_1 \neq \mathbf{\mu}_2$$

- In this case Uniformly Most Powerful test does not exist.
- However, we can resort to a suboptimum statistic that is called GLR

$$\Lambda(\mathbf{y}_1, \mathbf{y}_2) = \frac{\max_{\Theta} p(\mathbf{y}_1, \mathbf{y}_2 | \Theta, H_1)}{\max_{\Theta} p(\mathbf{y}_1, \mathbf{y}_2 | \Theta, H_0)}$$

 Here Θ stands for all the unknown parameters

• Given the Gaussian and independence assumptions we have

$$p(\mathbf{y}_1, \mathbf{y}_2 | \Theta, H) = \frac{1}{2\pi\sqrt{\det(\mathbf{R}_1)\det(\mathbf{R}_2)}} \exp\left[-\frac{1}{2}(\mathbf{y}_1 - \mathbf{\mu}_1)^T \mathbf{R}_1^{-1}(\mathbf{y}_1 - \mathbf{\mu}_1) - \frac{1}{2}(\mathbf{y}_2 - \mathbf{\mu}_2)^T \mathbf{R}_2^{-1}(\mathbf{y}_2 - \mathbf{\mu}_2)\right]$$

• We deduce immediately that

$$\max_{\Theta} p(\mathbf{y}_1, \mathbf{y}_2 | \Theta, H_0) = \frac{1}{2\pi \sqrt{\det(\hat{\mathbf{R}}_1) \det(\hat{\mathbf{R}}_2)}}$$

• To find the ML estimator of the mean under H_1 we use $\mu_1 = \mu_2 = \mu$ and equate partial derivative to 0:

$$\frac{\partial}{\partial \boldsymbol{\mu}} \ln p(\mathbf{y}_1, \mathbf{y}_2 | \boldsymbol{\Theta}, \boldsymbol{H}_1) = \mathbf{R}_1^{-1}(\mathbf{y}_1 - \boldsymbol{\mu}) + \mathbf{R}_2^{-1}(\mathbf{y}_2 - \boldsymbol{\mu}) = \overline{\mathbf{0}}$$

• Which results in the following expression for the ML estimator of the mean

$$\hat{\boldsymbol{\mu}} = \left[\mathbf{R}_1^{-1} + \mathbf{R}_2^{-1} \right]^{-1} \left[\mathbf{R}_1^{-1} \mathbf{y}_1 + \mathbf{R}_2^{-1} \mathbf{y}_2 \right]$$

 Substituting this estimator into likelihood ratio we get statistic of the form

$$\Lambda(\mathbf{y}_1, \mathbf{y}_2) = \exp\left[-\frac{1}{2}\Delta^T \hat{\mathbf{R}}_{\Delta}^{-1}\Delta\right]$$

• Where Δ is the difference between measurements:

$$\Delta = \mathbf{y}_1 - \mathbf{y}_2$$

• And the estimate of the covariance inverse has the following "nice" expression

$$\hat{\mathbf{R}}_{\Delta}^{-1} = \hat{\mathbf{R}}_{2}^{-1} \left[\hat{\mathbf{R}}_{1}^{-1} + \hat{\mathbf{R}}_{2}^{-1} \right]^{-1} \hat{\mathbf{R}}_{1}^{-1} \left[\hat{\mathbf{R}}_{1}^{-1} + \hat{\mathbf{R}}_{2}^{-1} \right]^{-1} \hat{\mathbf{R}}_{2}^{-1} + \\ + \hat{\mathbf{R}}_{1}^{-1} \left[\hat{\mathbf{R}}_{1}^{-1} + \hat{\mathbf{R}}_{2}^{-1} \right]^{-1} \hat{\mathbf{R}}_{2}^{-1} \left[\hat{\mathbf{R}}_{1}^{-1} + \hat{\mathbf{R}}_{2}^{-1} \right]^{-1} \hat{\mathbf{R}}_{1}^{-1}$$

 However, using the rule "the inverse of the product is equal to the product of inverses in reversed order" we can show that

$$\hat{\mathbf{R}}_{\Delta}^{-1} = \left[\hat{\mathbf{R}}_{1} + \hat{\mathbf{R}}_{2}\right]^{-1}$$

• Thus the geofeasibility score based on GLR admits the following simple and intuitive form

$$g_{G} \equiv \Lambda(\mathbf{y}_{1}, \mathbf{y}_{2})$$
$$g_{G} = \exp\left[-\frac{1}{2}\Delta^{T}\left[\hat{\mathbf{R}}_{1} + \hat{\mathbf{R}}_{2}\right]^{-1}\Delta\right]$$

Error bars, Monte-Carlo integration of the overlap area N=500



Monte Carlo Mean Squared Error, N=500



Monte-Carlo error for a fixed value of relative overlap area equal to 0.391



Comparison of statistics



Calculation time for 100,000 evaluations, Monte-Carlo. Calculation time for GLR is 4 seconds (0.04 ms/evaluation)



Questions