

Optimizing the design of a loyalty program

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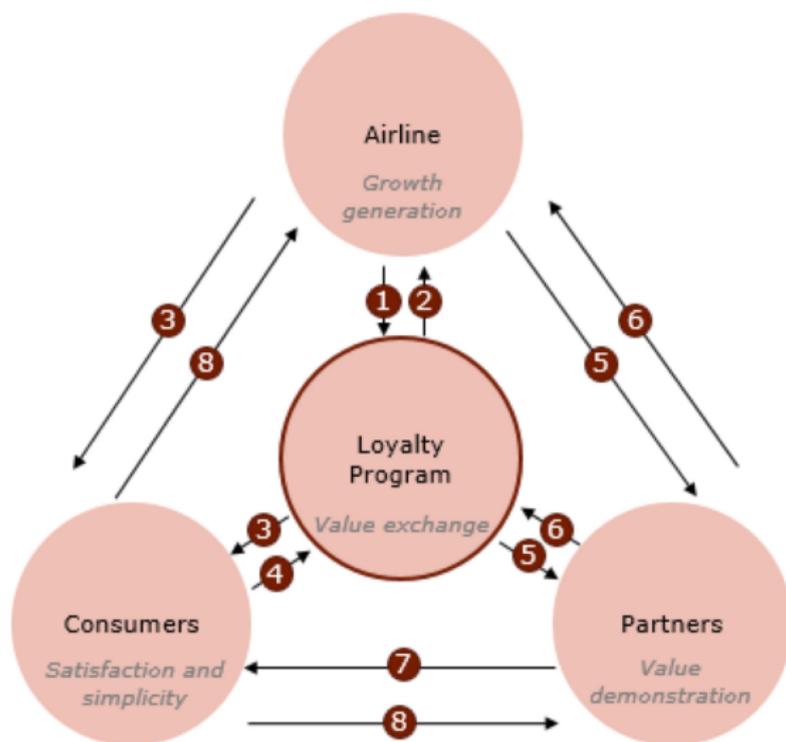
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Shaul

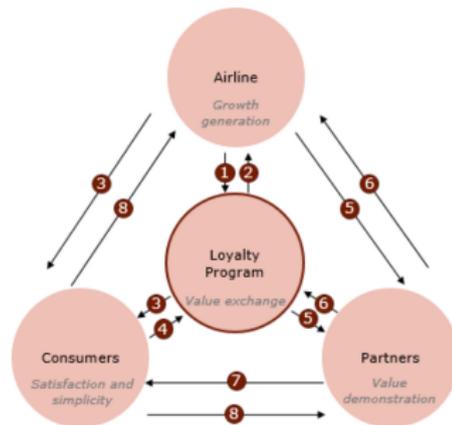
Centre de recherches mathématiques

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Aeroplan Loyalty Program



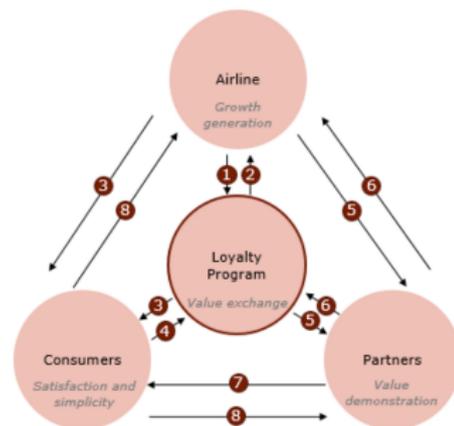
Aeroplan Loyalty Program



Aeroplan Loyalty Program

Accumulation

- ▶ Use Aeroplan-linked credit cards.
- ▶ Buy Air Canada (and other) flight tickets.



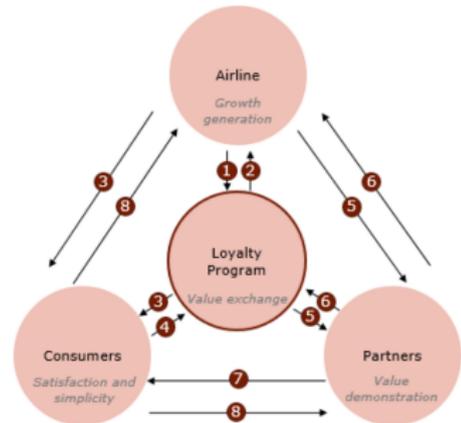
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Redemption

- ▶ Buy Air Canada (and other) flight tickets.
- ▶ Buy toasters etc.



Aeroplan Loyalty Program

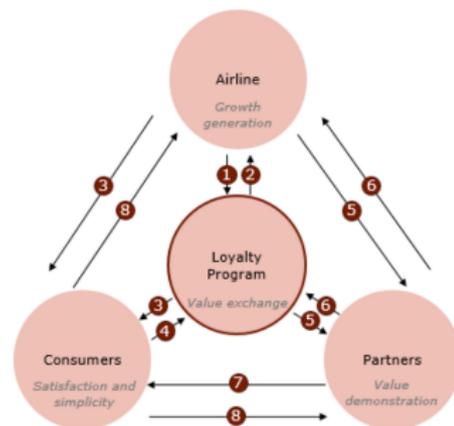
Accumulation

- ▶ Use Aeroplan-linked credit cards.
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- 1 *Members* collect points from *partners*.
- 2 *Partners* buy points from Aeroplan.

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Aeroplan Loyalty Program

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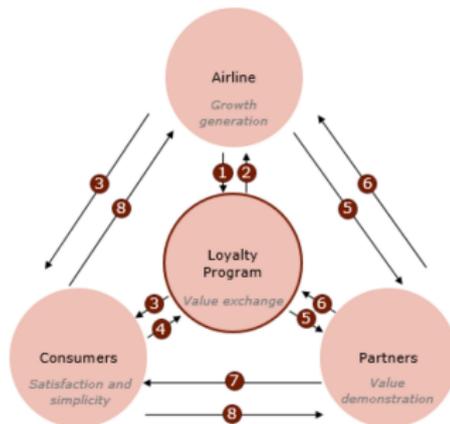
- ▶ Use Aeroplan-linked credit cards.
- ▶ Buy Air Canada (and other) flight tickets.

- 1 *Members* collect points from *partners*.
- 2 *Partners* buy points from Aeroplan.

Redemption

- ▶ Buy Air Canada (and other) flight tickets.
- ▶ Buy toasters etc.

- 1 Members use miles to get free tickets or toasters from Aeroplan.
- 2 Aeroplan pays the partner for the tickets and toasters.



Aeroplan's problem

$$\begin{array}{l} \max \\ \text{Miles per toaster} \\ \text{from member,} \\ \text{Budget, promotion,} \\ \text{etc.} \end{array} : \sum_{p,j} (\text{Revenue} - \text{Costs})$$

Subject to

- ▶ Some meaningful constraints

Aeroplan's problem

$$\begin{array}{l} \max \\ \text{Miles per toaster} \\ \text{from member,} \\ \text{Budget, promotion,} \\ \text{etc.} \end{array} : \sum_{P,j} (\text{Accumulated miles} \times P \rightarrow \text{AE Price} - \text{Costs})$$

Subject to

- ▶ Some meaningful constraints

Aeroplan's problem

$$\begin{array}{l} \max \\ \text{Miles per toaster} \\ \text{from member,} \\ \text{Budget, promotion,} \\ \text{etc.} \end{array} : \sum_{p,j} \left(d_{p,j}^{acc} \times \frac{P \rightarrow AE}{\pi_{p,j}} - \text{Costs} \right)$$

Subject to

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Aeroplan's problem

$$\begin{array}{l} \text{max} \\ \text{Miles per toaster} \\ \text{from member,} \\ \text{Budget, promotion,} \\ \text{etc.} \end{array} : \sum_{p,j} \left(d_{p,j}^{\text{acc}} \times \frac{P \rightarrow AE}{\pi_{p,j}} - \text{Redeem miles} \times \frac{AE \rightarrow P \text{ price per toaster}}{\text{miles per toaster}} \right)$$

Subject to

- ▶ Some meaningful constraints

Aeroplan's problem

$$\begin{array}{l} \max \\ \text{Miles per toaster} \\ \text{from member,} \\ \text{Budget, promotion,} \\ \text{etc.} \end{array} : \sum_{p,j} \left(d_{p,j}^{acc} \times \frac{P \rightarrow AE}{\pi_{p,j}} - d_{p,j}^{red} \frac{\frac{AE \rightarrow P}{\pi_{p,j}}}{m_{p,j}^{red}} \right)$$

Subject to

- ▶ Some meaningful constraints

Aeroplan's problem

$$\begin{array}{l} \max \\ \text{Miles per toaster} \\ \text{from member,} \\ \text{Budget, promotion,} \\ \text{etc.} \end{array} : \sum_{p,j} \left(d_{p,j}^{acc} \times \frac{P \rightarrow AE}{\pi_{p,j}} - d_{p,j}^{red} \frac{AE \rightarrow P}{m_{p,j}^{red}} \right)$$

– Promotion budget

Subject to

- ▶ Some meaningful constraints

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– Promotion budget – Budget to get new partners/members

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$$\begin{array}{l} \max \\ \text{Miles per toaster} \\ \text{from member,} \\ \text{Budget, promotion,} \\ \text{etc.} \end{array} : \sum_{p,j} \left(d_{p,j}^{acc} \times \frac{P \rightarrow AE}{\pi_{p,j}} - d_{p,j}^{red} \frac{AE \rightarrow P}{m_{p,j}^{red}} \right)$$

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$$\begin{array}{l} \max \\ \text{Miles per toaster} \\ \text{from member,} \\ \text{Budget, promotion,} \\ \text{etc.} \end{array} : \sum_{p,j} \left(d_{p,j}^{acc} \times \frac{P \rightarrow AE}{\pi_{p,j}} - d_{p,j}^{red} \frac{AE \rightarrow P}{m_{p,j}^{red}} \right)$$

– Promotion budget – Budget to get new partners/members

Subject to

- ▶ Budget balance constraints.
- ▶ Miles Accumulated in a year \geq Miles redeemed in a year

Aeroplan's problem

$$\begin{array}{l} \max \\ \text{Miles per toaster} \\ \text{from member,} \\ \text{Budget, promotion,} \\ \text{etc.} \end{array} : \sum_{p,j} \left(d_{p,j}^{acc} \times \frac{P \rightarrow AE}{\pi_{p,j}} - d_{p,j}^{red} \frac{AE \rightarrow P}{m_{p,j}^{red}} \right)$$

– Promotion budget – Budget to get new partners/members

Subject to

- ▶ Budget balance constraints.
- ▶ Miles Accumulated in a year \geq Miles redeemed in a year
- ▶ **Contract based promotions fulfilled.**

$$\begin{aligned}
& \max_{m_{p,j}^{red}, B_{AE}, a_{p,j}, \Psi} \lambda \left(\sum_k \left(\sum_{p \in \{FI, O\}} \sum_{j \in J_p} d_{M_k, p, j}^{acc} \frac{P \rightarrow AE}{\pi_{p,j}} - \sum_{p \in \{AC, FI, O\}} \sum_{j \in J_p^{red}} d_{M_k, p, j}^{red} \frac{AE \rightarrow P}{m_{p,j}^{red}} \right) \right. \\
& \quad \left. - B_{AE} + f(\Psi) + \sum_k \sum_{j \in J_{AC}} (p_{j,k}^{acc} s_{j,k}^{acc} + p_{j,k}^{red} s_{j,k}^{red}) - B_{AC} \right) \\
& \quad + (1 - \lambda) \left(\sum_k \sum_{p \in \{AC, FI, O\}} \sum_{j \in J_p} g(d_{M_k, p, j}^{acc}) \right) \tag{1a}
\end{aligned}$$

subject to

$$\sum_{p \in \{AC, FI, O\}} \sum_{j \in J_p} a_{p,j} + \Psi \leq B_{AE} \tag{1b}$$

$$\sum_k \sum_{p \in \{AC, FI, O\}} \sum_{j \in J_p} d_{M_k, p, j}^{red} \leq \sum_k \sum_{p \in \{AC, FI, O\}} \sum_{j \in J_p} d_{M_k, p, j}^{acc} \tag{1c}$$

$$a_{p,j} \geq l_{p,j} \quad \forall p, j \tag{1d}$$

Partners' problem

$$\max_{\substack{\text{Miles acc} \\ \text{per toaster,} \\ \text{Budget, promotion,} \\ \text{etc.}}} : \sum \text{Addnl profit due to partnership} - \text{Cost of partnership}$$

Subject to

- ▶ Some meaningful constraints

Partners' problem

$$\begin{array}{l} \max \\ \text{Miles acc} \\ \text{per toaster,} \\ \text{Budget, promotion,} \\ \text{etc.} \end{array} : \sum \text{Accum profit} + \text{Redem profit} - \text{Cost of partnership}$$

Subject to

- ▶ Some meaningful constraints

Partners' problem

$$\begin{array}{l} \max \\ \text{Miles acc} \\ \text{per toaster,} \\ \text{Budget, promotion,} \\ \text{etc.} \end{array} : \sum p_j^{acc} s_j^{acc} + p_j^{red} s_j^{red} - \text{Cost of partnership}$$

Subject to

- ▶ Some meaningful constraints

Partners' problem

$$\begin{array}{l} \max \\ \text{Miles acc} \\ \text{per toaster,} \\ \text{Budget, promotion,} \\ \text{etc.} \end{array} : \sum p_j^{acc} s_j^{acc} + p_j^{red} s_j^{red} - (\text{Accum miles} \times P \rightarrow \text{AE Price} + B)$$

Subject to

- ▶ Some meaningful constraints

Partners' problem

$$\begin{array}{l} \max \\ \text{Miles acc} \\ \text{per toaster,} \\ \text{Budget, promotion,} \\ \text{etc.} \end{array} : \sum p_j^{\text{acc}} s_j^{\text{acc}} + p_j^{\text{red}} s_j^{\text{red}} - (d_{p,j}^{\text{acc}} \times \frac{P \rightarrow AE}{\pi_{p,j}} + B)$$

Subject to

- ▶ Some meaningful constraints

Partners' problem

$$\begin{array}{l} \max \\ \text{Miles acc} \\ \text{per toaster,} \\ \text{Budget, promotion,} \\ \text{etc.} \end{array} : \sum p_j^{acc} s_j^{acc} + p_j^{red} s_j^{red} - (d_{p,j}^{acc} \times \frac{P \rightarrow AE}{\pi_{p,j}} + B)$$

Subject to

- ▶ $d_{p,j}^{acc} = s_j^{acc} m_{p,j}^{acc}$
- ▶ $d_{p,j}^{red} = s_j^{red} m_{p,j}^{red}$

Partners' problem

$$\begin{array}{l} \max \\ \text{Miles acc} \\ \text{per toaster,} \\ \text{Budget, promotion,} \\ \text{etc.} \end{array} : \sum p_j^{acc} s_j^{acc} + p_j^{red} s_j^{red} - (d_{p,j}^{acc} \times \frac{P \rightarrow AE}{\pi_{p,j}} + B)$$

Subject to

- ▶ $d_{p,j}^{acc} = s_j^{acc} m_{p,j}^{acc}$
- ▶ $d_{p,j}^{red} = s_j^{red} m_{p,j}^{red}$
- ▶ Budget balance constraint.

Partners' problem

$$\begin{array}{l} \max \\ \text{Miles acc} \\ \text{per toaster,} \\ \text{Budget, promotion,} \\ \text{etc.} \end{array} : \sum p_j^{acc} s_j^{acc} + p_j^{red} s_j^{red} - (d_{p,j}^{acc} \times \frac{P \rightarrow AE}{\pi_{p,j}} + B)$$

Subject to

- ▶ $d_{p,j}^{acc} = s_j^{acc} m_{p,j}^{acc}$
- ▶ $d_{p,j}^{red} = s_j^{red} m_{p,j}^{red}$
- ▶ Budget balance constraint.
- ▶ **Stock availability constraint**

Partners' problem

$$\begin{array}{l} \max \\ \text{Miles acc} \\ \text{per toaster,} \\ \text{Budget, promotion,} \\ \text{etc.} \end{array} : \sum p_j^{acc} s_j^{acc} + p_j^{red} s_j^{red} - (d_{p,j}^{acc} \times \frac{P \rightarrow AE}{\pi_{p,j}} + B)$$

Subject to

- ▶ $d_{p,j}^{acc} = s_j^{acc} m_{p,j}^{acc}$
- ▶ $d_{p,j}^{red} = s_j^{red} m_{p,j}^{red}$
- ▶ Budget balance constraint.
- ▶ Stock availability constraint $s_j^{acc} + s_j^{red} \leq \alpha_j$ and $s_j^{red} \leq \beta_j$.

Partners' problem

$$\begin{array}{l} \max \\ \text{Miles acc} \\ \text{per toaster,} \\ \text{Budget, promotion,} \\ \text{etc.} \end{array} : \sum p_j^{acc} s_j^{acc} + p_j^{red} s_j^{red} - (d_{p,j}^{acc} \times \frac{P \rightarrow AE}{\pi_{p,j}} + B)$$

Subject to

- ▶ $d_{p,j}^{acc} = s_j^{acc} m_{p,j}^{acc}$
- ▶ $d_{p,j}^{red} = s_j^{red} m_{p,j}^{red}$
- ▶ Budget balance constraint.
- ▶ Stock availability constraint $s_j^{acc} + s_j^{red} \leq \alpha_j$ and $s_j^{red} \leq \beta_j$.

Note: Air Canada's problem can be concatenated with Aeroplan's.

$$\max_{m_{p,j}^{acc}, B_p, b_{p,j}} \sum_k \left(\sum_{j \in J_p} \left(p_{j,k}^{acc} s_{j,k}^{acc} - d_{M_k, p, j}^{acc} \frac{P \rightarrow AE}{\pi} p_{p,j} \right) + \sum_{j \in J_p^{red}} p_{j,k}^{red} s_{j,k}^{red} \right) - B_p \quad (2a)$$

subject to

$$\sum_{j \in J_p} b_{p,j} \leq B_p \quad (2b)$$

$$d_{M_k, p, j}^{acc} = s_{j,k}^{acc} m_{p,j}^{acc} \quad (2c)$$

$$d_{M_k, p, j}^{red} = s_{j,k}^{red} m_{p,j}^{red} \quad (2d)$$

$$\sum_k s_{j,k}^{acc} + s_{j,k}^{red} \leq \alpha_j \quad (2e)$$

$$\sum_k s_{j,k}^{red} \leq \beta_j \quad (2f)$$

A regression model

$$s_{k,p,j,t}^{acc} = \mathcal{R} \left(\{m_{p,j,t-1}^{red}\}_{p,j}, m_{p,j,t}^{acc}, a_{p,j}, b_{p,j} \right) \quad (3a)$$

$$s_{k,p,j,t}^{red} = \mathcal{R} \left(\{m_{p,j,t}^{red}\}_{p,j}, s_{k,p,j,t-1}^{acc}, m_{p,j,t-1}^{acc}, a_{p,j}, b_{p,j} \right) \quad (3b)$$

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One predicts the number of each product bought for the sake of accumulating miles or for redeeming miles using a regression model (perhaps a neural network), given

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- ▶ The miles accumulated in previous time period
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- ▶ Promotion efforts by Aeroplan
- ▶ Promotion efforts by the partner

A regression model

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- ▶ Perhaps member type? Literacy in the program, income level?

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- ▶ Promotion efforts by Aeroplan
- ▶ Promotion efforts by the partner
- ▶ Perhaps member type? Literacy in the program, income level?
- ▶ Other interesting parameters?

Question.

Why is this problem hard?

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Why is this problem hard?

- ▶ The optimization problems are coupled.
 - ▶ The price $\frac{P \rightarrow AE}{\pi_{p,j}}$ affects both the partner and AE and an agreement has to be reached.
 - ▶ Aeroplan's decision $m_{p,j}^{red}$ directly determines Aeroplan's revenue and decides a parameter influencing partner's profit.

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 - ▶ Partner's decision of $m_{p,j}^{acc}$ affects Aeroplan's revenue.

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- ▶ We need a solution that *simultaneously* optimizes all players' optimization problems.

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Welcome to Game theory

Example: Prisoner's dilemma

The prisoners simultaneously select their strategy.

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		Prisoner B			
		silent		betray	
Prisoner A	silence	-1	-1	-3	0
	betray	0	-3	-2	-2

Example: Prisoner's dilemma

The prisoners simultaneously select their strategy.

There is a unique Nash equilibrium:

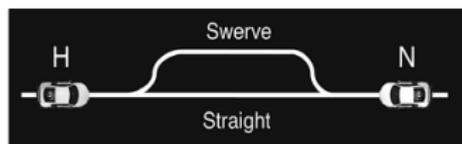
(betray, betray)

		Prisoner B			
		silent		betray	
Prisoner A	silence	-1	-1	-3	0
	betray	0	-3	-2	-2

Example: game of chicken

Simultaneously, the cars decide to swerve and straight.

		Car B			
		Swerve		Straight	
Car A	Swerve	tie 0	tie 0	lose -1	win +1
	Straight	win +1	lose -1	accident -1000	accident -1000



origem: www.researchgate.net/publication/261351299_The_effects_of_neuromodulation_on_human-robot_interaction_in_games_of_conflict_and_cooperation/figures?lo=1&utm_source=google&utm_medium=organic

Example: game of chicken

Simultaneously, the cars decide to swerve and straight.

There are 3 equilibria:

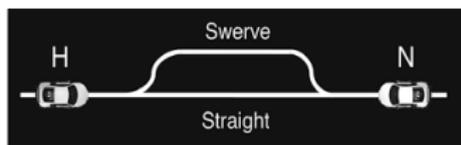
Car A: swerve and Car B: straight

Car A: straight and Car B: swerve

Car A: swerve with prob $\frac{999}{1000}$ and straight with prob $\frac{1}{1000}$

Car B: swerve with prob $\frac{999}{1000}$ and straight with prob $\frac{1}{1000}$

		Car B			
		Swerve		Straight	
Car A	Swerve	tie 0	tie 0	lose -1	win +1
	Straight	win +1	lose -1	accident -1000	accident -1000

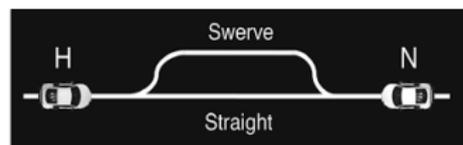


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Example: game of chicken

Simultaneously, the cars decide to swerve and straight.

There is a correlated equilibrium where:

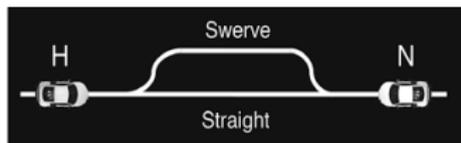
Car A and Car B get a positive utility!

Car A plays *swerve* and Car B plays *swerve* with prob $\frac{998}{1000}$,

Car A plays *swerve* and Car B plays *straight* with prob $\frac{997}{1000^2}$

Car A plays *straight* and Car B plays *swerve* with prob $\frac{999}{1000^2}$

		Car B			
		Swerve		Straight	
Car A	Swerve	tie 0	tie 0	lose -1	win +1
	Straight	win +1	lose -1	accident -1000	accident -1000



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Example: game of chicken

Simultaneously, the cars decide to swerve and straight.

Moral: by sending signals players can find a more balanced solutions.

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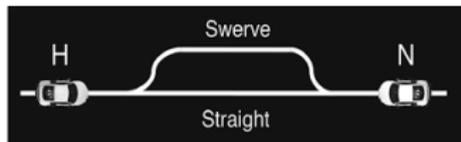
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Car A plays *straight* and Car B plays *swerve* with prob $\frac{999}{1000^2}$

		Car B			
		Swerve		Straight	
Car A	Swerve	tie 0	tie 0	lose -1	win +1
	Straight	win +1	lose -1	accident -1000	accident -1000



origem: www.researchgate.net/publication/261351299_The_effects_of_neuromodulation_on_human-robot_interaction_in_games_of_conflict_and_cooperation/figures?lo=1&utm_source=google&utm_medium=organic

Algorithmic approach: literature

Normal form games can be solved *reasonably fast* to obtain a *mixed-strategy Nash or correlated equilibrium*.

Players have a finite number of strategies and the game is represented through a multidimensional matrix with an entry for each pure profile of strategies.

		Player 2		
		rock	scissors	paper
Player 1	rock	(0,0)	(1,-1)	(-1,1)
	scissors	(-1,1)	(0,0)	(1,-1)
	paper	(1,-1)	(-1,1)	(0,0)

Table: Rock-scissors-paper game

Algorithmic approach: overview

- Step 1** Compute an initial set of strategies for each player.
- Step 2** Obtain the normal-form game associated with the enumerated strategies.
- Step 3** Compute the equilibria of the current normal-form game.
- Step 4** Determine whether there is a player with incentive to deviate. If the deviation incentive is greater than a certain tolerance, update the normal-form game with new strategies and go back to **Step 3**. Else, **return** the current equilibrium.

Step 1: Initial set of strategies

- ▶ Current strategies of the players.
- ▶ Strategies that guarantee a minimum profit for each player.
- ▶ Optimal strategies if each player controlled the remaining ones.
- ▶ Equilibrium strategies for subsets of players.
- ▶ etc...

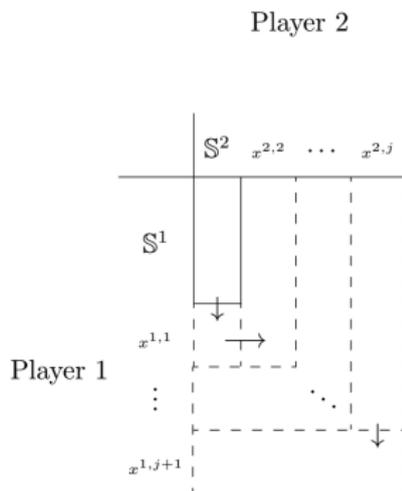
Depending on this initialization the algorithm convergence rate will vary.

Let \mathbb{S}_p be the initial set of pure strategies for player p .

Step 2: Normal-form Game

Compute the utility of each player for any combination of strategies and build the associated multidimensional matrix.

Step 3: Compute the Equilibria



Nash equilibria: there are solvers available.
Correlated equilibria: there is a solver for 2-player game.

Step 4: Verify Nash Equilibria

For an equilibrium x^* , for each player p solve

$$\hat{x}_p = \operatorname{argmax}_{x_p \in X_p} f_p(x_p, x_{-p}^*)$$

If $f_p(\hat{x}_p, x_{-p}^*) - f(x^*) \leq \epsilon \quad \forall p$ then return x^* .
Otherwise, add \hat{x}_p to the normal-form game.

Step 4: Verify Correlated Equilibria

For an equilibrium σ^* (probability distribution over any outcome of the normal-form game), for each player p and for each $x_p \in \mathbb{S}_p$ (strategies in the current normal-form game) solve

$$z_p = \min_{\hat{x}_p \in X_p} \sum_{x_{-p} \in \mathbb{S}_{-p}} \sigma^*(x_p, x_{-p}) f_p(x_p, x_{-p}) - \sum_{x_{-p} \in \mathbb{S}_{-p}} \sigma^*(x_p, x_{-p}) f_p(\hat{x}_p, x_{-p})$$

If z_p is negative then σ^* is not a correlated equilibrium and \hat{x}_p must be added to the game.

Otherwise, if $z_p \geq 0 \quad \forall p \forall x_p \in \mathbb{S}_p$, return σ^* .

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Probably-based strategy profile can be hard to implement.

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- ▶ If the game is only played a few times, maximizing *expected* returns does not make sense.
- ▶ A deterministic equilibrium might fail to exist! (Example: Rock-Paper-Scissors).
- ▶ Are there intelligent hacks to implementing the equilibrium?

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- ▶ Each partner's presence increases the total value generated.
- ▶ The grand coalition between Aeroplan and *all* the partners creates a total increased utility.
- ▶ How can the dollar value of the utility be distributed among the partners and Aeroplan - in a fair and acceptable way?

Notions of cooperative game theory

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 - ▶ Downside: No existence guarantees! (But in practice, many interesting games have a core)
- ▶ These notions give indications to Aeroplan on who has the market power and where the fair rates are for each partner.

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 - ▶ Ideas from Vielma et. al. (2018) [arxiv:1811.01988].
- ▶ Interesting hacks to implement a probability-based equilibrium.

Thank you

Solution Concepts

Definition (Correlated Equilibrium. Aumann 1974)

Let $\Gamma = \langle I, (A_i)_{i \in I}, (u_i)_{i \in I} \rangle$ be a strategic form game. A *Correlated Equilibrium* is a distribution $\mu \in \Delta(A)$ such that

$$\forall i \in I, \forall a_i, a'_i \in A_i, \sum_{a_{-i} \in A_{-i}} \mu(a_i, a_{-i}) [u_i(a_i, a_{-i}) - u_i(a'_i, a_{-i})] \geq 0.$$



Figure: An example of a Correlated Equilibrium.

Nash Equilibrium

Definition (Nash Equilibrium. Nash, 1950)

Let $\Gamma = \langle I, (A_i)_{i \in I}, (u_i)_{i \in I} \rangle$ be a strategic form game. A mixed strategy of player i is a probability measure over A_i , we denote the set of mixed strategy profiles of player i as Δ_i . A mixed strategy profile $\delta^* = (\delta_i^*)_{i \in I}$ is a mixed Nash Equilibrium iff

$$\forall i \in I, \forall \delta_i \in \Delta_i, u_i(\delta_i^*, \delta_{-i}) - u_i(\delta_i, \delta_{-i}) \geq 0.$$

Remark A mixed Nash Equilibrium is a Correlated Equilibrium where the players' mixed strategies are independent.

Definition (Core)

For a Cooperative Game (N, v) , a payoff distribution

$\mathbf{x} = (x_1, \dots, x_n) \in \mathbb{R}^n$ is

- ▶ *efficient* if $\sum_{i \in N} x_i = v(N)$,
- ▶ *individually rational* if for every $i \in N$, $x_i \geq v(\{i\})$,
- ▶ *coalitionally rational* if for every $B \in 2^N \setminus \emptyset$, $\sum_{i \in B} x_i \geq v(\{B\})$.

The *Core* of (N, v) is the set

$C(N, v) = \{\mathbf{x} \in \mathbb{R}^n \mid \mathbf{x} \text{ is efficient and coalitionally rational}\}$

Remark The Core could be large, small or even empty.

Definition (Shapley value)

The Shapley value of a cooperative game (N, v) is a payoff vector $\Phi(N, v)$ whose i -th coordinate is

$$\Phi_i(N, v) = \sum_{B \subseteq N: i \notin B} \frac{|B|!(n-|B|-1)!}{n!} [v(B \cup \{i\}) - v(B)].$$

Remark The Shapley value assigns to each player her average marginal contribution to the game.

Note that the Shapley value might not be in the Core.