

Simulation of Extreme Events in the Presence of Spatial Dependence

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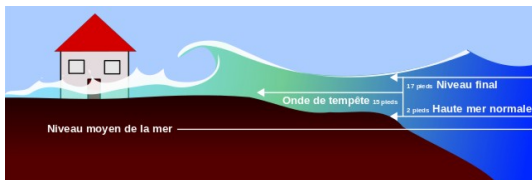
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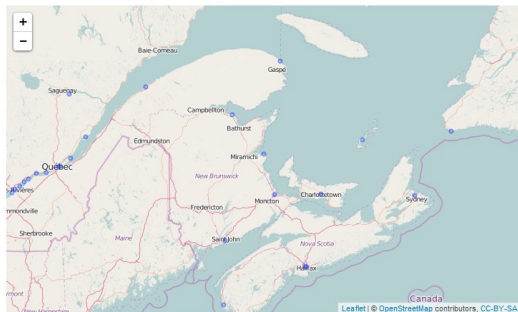
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Problem

- Evaluate the risk of **coastal floods** (from salt water)
- Deterministic model for the propagation of water in land
- Create a model to **simulate water levels** on the coast
- Capture spatial dependence to evaluate risk properly



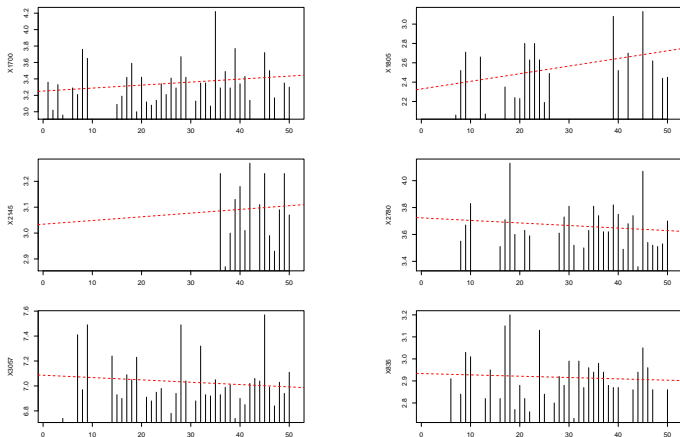
Data and related choices



- Measure from tide gauges
- 21 locations, east of Québec City
- (at most) 50 years of data (much fewer in some locations)
- Interest in Z , the **annual maximum** water level
- L , the normal (theoretical) **level of a high tide** is known
- **Longitude** and **latitude** used for location

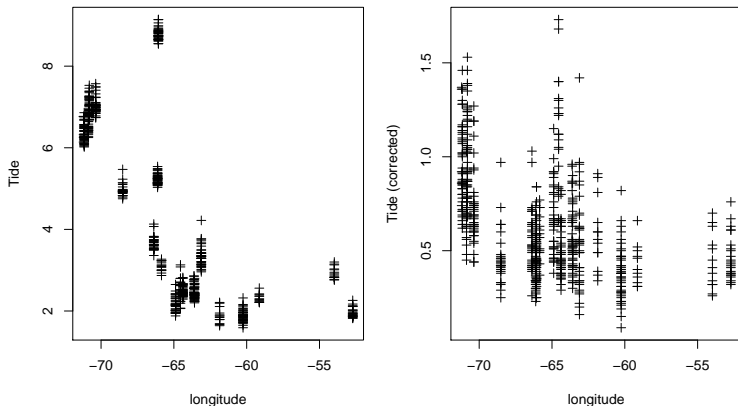
Working hypothesis #1

No temporal trends in the annual maxima



Shown above : Annual maximum vs year at 6 different sites.
Climate change ignored : insurance contract are for one year.

Spatial trend in mean



Annual maxima vs longitude.

Left : raw data (Z) ; Right : corrected for tide level ($Z - L$)

Notation

- Let a random fields $Z(s)$, where $Z(s)$ are annual maxima at location $s \in \mathbb{R}^2$
- Joint distribution

$$H(z_1, \dots, z_n) = Pr \{Z(s_1) \leq z_1, \dots, Z(s_n) \leq z_n\}$$

Looking for a model for H

- Marginal model — Generalized Extreme Value
- Spatial model — t Copula
- Solution #1 : Frequentist approach
- Solution #2 : Bayesian approach
- Conclusion

Theorem (Fisher-Tippett)

Let Y_1, \dots, Y_m be an iid sequence of variables and $Z_m = \max\{Y_1, \dots, Y_m\}$. If there exists some $b_m > 0$ and $a_m \in \mathbb{R}$ such that

$$\frac{Z_m - a_m}{b_m} \rightsquigarrow H,$$

for some non-degenerate distribution H , then H has a generalized extreme value (GEV) distribution, that is

$$F(y; \mu, \sigma, \xi) = \begin{cases} \exp \left\{ - \left(1 + \xi \frac{y - \mu}{\sigma} \right)^{-1/\xi} \right\}, & \xi \neq 0, 1 + \xi \frac{y - \mu}{\sigma} > 0 \\ \exp \left\{ - \exp \left(- \frac{y - \mu}{\sigma} \right) \right\}, & \xi = 0, y \in \mathbb{R}. \end{cases}$$

In particular, when m is large enough,

$$Z_m \approx GEV(\mu, \sigma, \xi)$$

and this approximation holds true even if Y_1, \dots, Y_m is not independent.

- short/medium range autocorrelation "disappears" when taking maximum (yay !)

Decomposition

$$H(z_1, \dots, z_{21}) = C_{\Sigma_{\theta, \gamma}} \{F_{\beta_1}(z_1), \dots, F_{\beta_{21}}(z_{21})\}$$

- $C_{\Sigma_{\theta, \gamma}}$ is a copula and F_{β} are marginal distributions
- $(\Sigma_{\theta, \gamma})_{ij} = g_{\gamma} \left(\frac{\delta_{ij}}{\theta} \right)$
- Isotropic random field

Student copula

- Non zero upper tail dependence

$$\lambda_U = \lim_{u \rightarrow 1^-} Pr \left\{ X_1 > F_1^{-1}(u) \mid X_2 > F_2^{-1}(u) \right\}$$

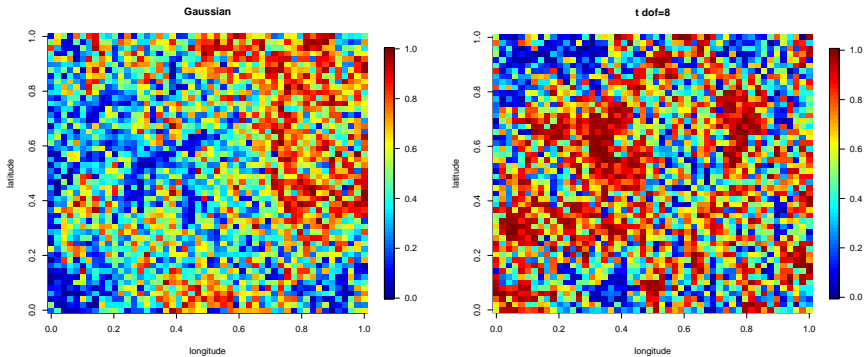
- Close under margins

Power exponential model

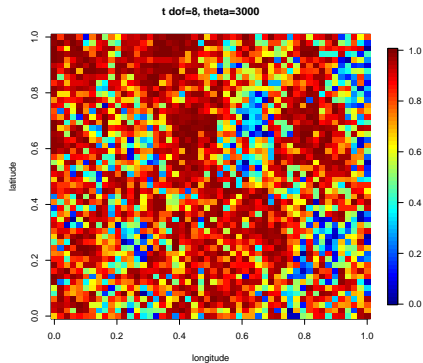
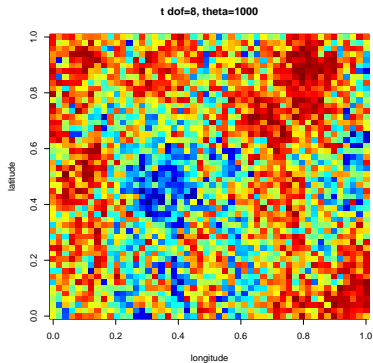
$$g_\nu(\delta) = \exp \left[-3 \left(\frac{\delta}{\theta} \right)^\gamma \right]$$

where θ is a range parameter and γ is a smoothness parameter.

Effect of the tail dependence

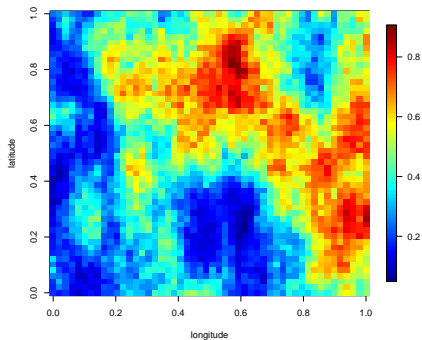


Effect of the range parameter θ

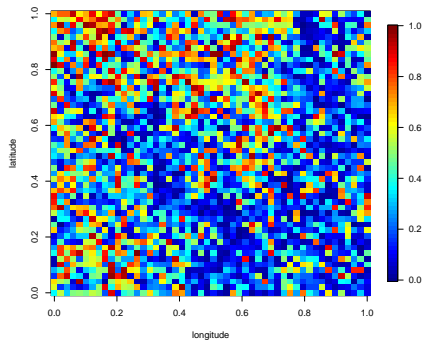


Effect of the smoothness parameter γ

t dof=8, nu=1



t dof=8, nu=0.2



Marginal GEV model

- Marginal distribution with covariates

$$(Z - L) = Z^* \rightarrow \text{GEV}(\mu(s_{lon}), \sigma, \xi)$$

- Location : $\mu(s_{lon}) = a_0 + a_1 s_{lon} + a_2 s_{lon}^2$
- Constant scale σ and shape ξ
- Likelihood for the marginal

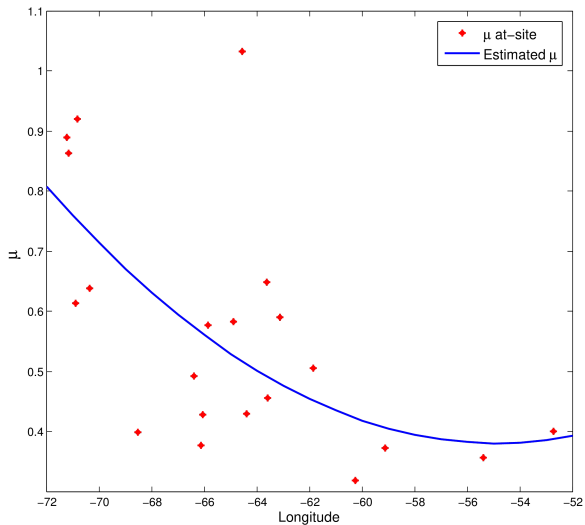
$$\mathcal{L}(a_0, a_1, a_2, \sigma, \xi) = \prod_{k=1}^{n^*} f(z_k; a_0, a_1, a_2, \sigma, \xi)$$

where n^* = number of year-site

Marginal GEV model

- $\hat{\mu} = 4.74 + 0.16s_{long} + 0.002s_{long}^2$
- $\hat{\sigma} = 0.20$
- $\hat{\xi} = 0.07$

Estimation of the location parameters μ



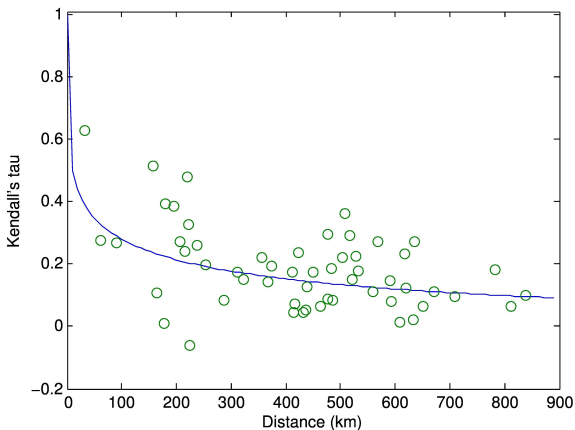
Copula estimation

- Marginal parameters are known : $\hat{\beta}_i = (\hat{\mu}_i, \hat{\sigma}, \hat{\xi})$
- Second step : Pseudo-likelihood

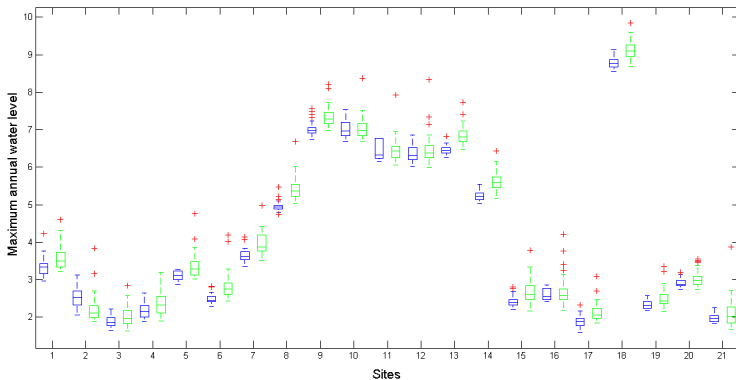
$$\mathcal{L}(\theta, \gamma) = \prod_{i=1}^n c_{\Sigma_{\theta, \gamma}}^{(d_i)} \left\{ F_{\hat{\beta}_1}(Z_{i,1}), \dots, F_{\hat{\beta}_{d_i}}(Z_{i,d_i}) \right\},$$

where d_i is the number of non missing sites at time $i = 1, \dots, n$.

Evolution of the dependence ($\hat{\theta} = 2850$, $\hat{\gamma} = .37$ $df = 21$)



Boxplot of simulated (green) vs true (blue) values



Hierarchical Bayesian model

1) Data level

$\mathbf{Z}(\mathbf{s})|\theta$ has copula C_θ and

$$Z(\mathbf{s}_i)|\mu(\mathbf{s}_i), \sigma, \xi \sim GEV(\mu(\mathbf{s}_i), \sigma, \xi)$$

2) Process level

Non-informative priors are used for σ, ξ and $\theta = (\theta_1, \theta_2)$ and $(\boldsymbol{\mu}(\mathbf{s})|\boldsymbol{\beta}, \tau, \varrho) \sim \mathcal{N}_d$.

3) Hyper priors

$\boldsymbol{\beta} = (\beta_0, \beta_1)$ and ϱ have non-informative priors and τ has a non-informative prior.

Hierarchical Bayesian model

Given the parameters μ, σ, ξ and θ , the joint distribution of the maxima is

$$F_{\mathbf{z}|\mu,\sigma,\xi,\theta}(\mathbf{z}) = C_{\theta} [F\{z(s_1)|\mu_1, \sigma, \xi\}, \dots, F\{z(s_d)|\mu_d, \sigma, \xi\}],$$

where

- C_{θ} is a t copula
- F is the cdf of the GEV distribution.

Fitting is performed by MCMC.

Hierarchical Bayesian model — copula parameters

The degrees of freedom of the t copula are fixed.

The correlation depends on the distance between the stations :

$$\rho_z(\mathbf{s}_i, \mathbf{s}_j) = \theta_1 \text{dist}(s_i, s_j)^{\theta_2},$$

with f_{θ_1} is $\mathcal{U}(0, 1)$ and f_{θ_2} is $\mathcal{U}(0, 2)$.

Hierarchical Bayesian model — marginal parameters

At the process level, we use non-informative priors for σ and ξ , while, for $\mathbf{s} = (s_1, \dots, s_d)$,

$$\boldsymbol{\mu}(\mathbf{s}) \sim \mathcal{N}_d(X(\mathbf{s})\boldsymbol{\beta}, \Sigma(\mathbf{s})),$$

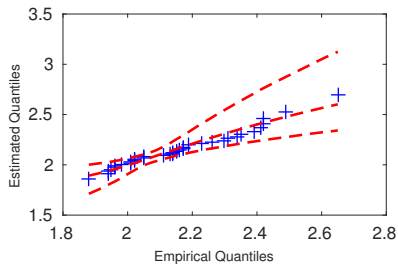
where

- $X(s_i)\boldsymbol{\beta} = \beta_0 + \beta_1 x_i$ and x_i is the deterministic predicted maximum tide level at station s_i ,
- $\Sigma(\mathbf{s}) = (\rho_\mu(s_i, s_j))_{d \times d}$, with

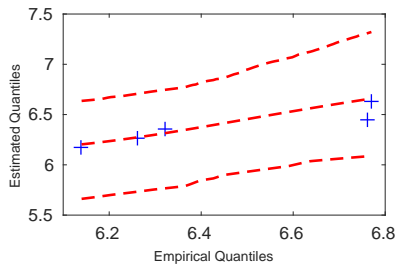
$$\rho_\mu(s_i, s_j) = \tau \exp(-\text{dist}(s_i, s_j)/\varrho).$$

A non-informative prior was used for $\boldsymbol{\beta}$, f_ϱ is $\mathcal{U}(0, \max_{i,j}\{\text{dist}(s_i, s_j)\})$ and $f_\tau(\tau) \propto 1/\tau$.

Goodness of fit testing



(a) Station 2



(b) Station 11

FIGURE – QQ Plots for GEV margins

Goodness of fit testing (cont.)

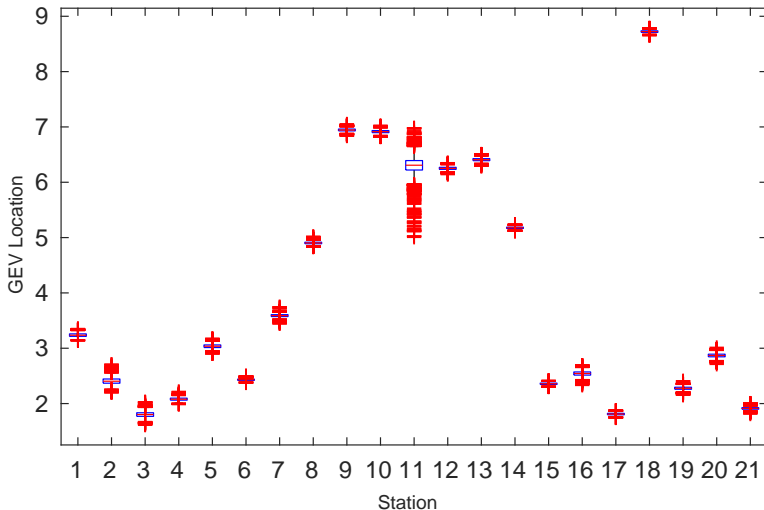


FIGURE – Boxplots for stations' location parameter

Simulation from this model can be done with the following (simple !) algorithm :

- (1) Generate the parameters $\beta, \tau, \varrho, \boldsymbol{\mu}(\mathbf{s}), \sigma, \xi$ and θ
- (2) Generate realization from the copula C_θ , i.e. $\mathbf{u} = (u_1, \dots, u_d)$
- (3) Using the GEV margins, invert the copula realizations using $x_i = F^{-1}(u_i | \mu(\mathbf{s}_i), \sigma, \xi), i = 1, \dots, d.$

Can also be used for interpolation between sites as the hierarchical structure accounts for spatiality.

Conclusion

- Applicable model with reasonable results
- Scalable
- Annual maxima vs multiple claims the same year
- Room to improve the modelling of μ and σ
- Need to check the fit on simultaneous data
- Great team !