

Finite element analysis of ultralight metallic lattices

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Problem submitted by

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- **Context** : Additive manufacturing (3D printing)

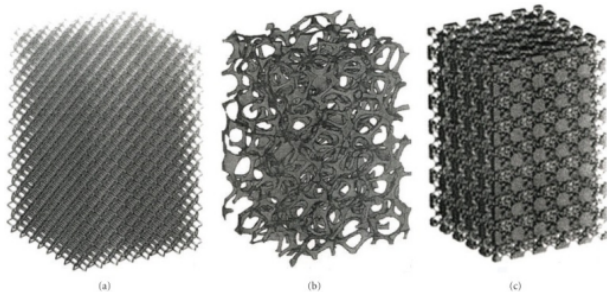


FIGURE: Source : <http://openi.nlm.nih.gov/>

- **Goal** : use ultralight lattice structures to reduce weight of pieces of machinery while preserving or improving their characteristics.
- **Problem** : Because of the small size of the cells ($\leq 1\text{mm}$), number of Finite Elements required for the computational analysis is huge.

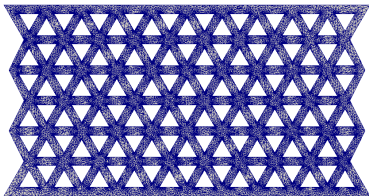


FIGURE: Adapted mesh for a 2D plate lattice

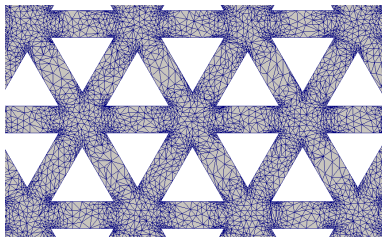


FIGURE: Zoom in

- **Goal of the project** : Find a model (equations for the displacement, temperature) that can be discretized and solved numerically at a reasonable cost and within a reasonable time
- **Research avenues** :
 - 1 use **beam models** (but struts are irregular and struts diameters are not small compared to cells sizes)
 - 2 use directly a **discrete model** of interacting nodes dictated by the lattice structures (but we need to find the laws of interaction between the nodes)
 - 3 find a **replacement homogeneous solid** with equivalent mechanical properties to those of the original piece

We followed the 3rd avenue, using **homogenization** theory.

Specificities of the applications

The engine parts that PWC has in mind are very thin (with shell like shape), thus with only a very small number of cell layers (between 4 and 10).

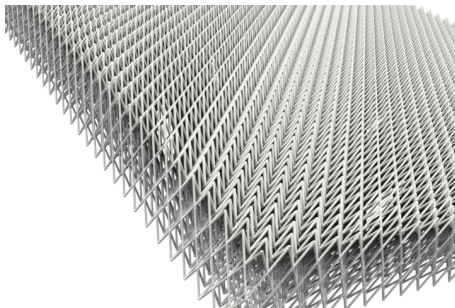


FIGURE: 3D plate lattice (source : <http://architectedmaterials.com/>)

A model diffusion problem on a plate

Ω = horizontal plate in the (x_1, x_2, x_3) coordinate system, with periodic inhomogeneities.

ε = characteristic length of a cell

$$\begin{cases} -\operatorname{div} \left(A \left(\frac{\mathbf{x}}{\varepsilon} \right) \nabla u_\varepsilon(\mathbf{x}) \right) = f & \text{in } \Omega, \\ A \nabla u_\varepsilon \cdot \mathbf{n} = 0 & \text{on } \partial\Omega. \end{cases} \quad (0.1)$$

Two-scale method (see G. Allaire [2007]) :

$$u_\varepsilon(\mathbf{x}) = u_0(\mathbf{x}, y) + \varepsilon u_1(\mathbf{x}, y) + \varepsilon^2 u_2(\mathbf{x}, y) + \dots$$

where $y = \mathbf{x}/\varepsilon \in Y = [0, 1]^3$ (scaled unit cell) is a **microscale** variable. Inserting this expansion into the PDE we obtain equations for u_0, u_1, u_2, \dots beginning with the lowest order (in ε) terms.

After a few manipulations :

$$u_0(\mathbf{x}, \mathbf{y}) = u(\mathbf{x}).$$

$$u_1(\mathbf{x}, \mathbf{y}) = \sum_{i=1}^3 \frac{\partial u(\mathbf{x})}{\partial x_i} w_i(\mathbf{y}).$$

where w_i is the solution of

$$\begin{cases} \operatorname{div}_{\mathbf{y}} (A(\mathbf{y})(\mathbf{e}_i + \nabla_{\mathbf{y}} w_i(\mathbf{y}))) = 0 & \text{in } Y, \\ w_i(\mathbf{y}) \text{ periodic} & \text{on } \partial Y. \end{cases} \quad (0.2)$$

$$-\operatorname{div}_{\mathbf{y}} (A \nabla_{\mathbf{y}} u_2) = \operatorname{div}_{\mathbf{y}} (A \nabla_{\mathbf{x}} u_1) + \operatorname{div}_{\mathbf{x}} (A (\nabla_{\mathbf{x}} u + \nabla_{\mathbf{y}} u_1)) + f.$$

and, last but not least, the (very nice) homogeneous problem

$$-\operatorname{div}_{\mathbf{x}} (A^* \nabla_{\mathbf{x}} u) = f(\mathbf{x}) \quad \text{in } \Omega, \quad (0.3)$$

where A^* is called the homogenized tensor and can be computed at the cell level :

$$A_{ij}^* := \int_Y A(\mathbf{y}) (\mathbf{e}_j + \nabla_{\mathbf{y}} w_j) \cdot \mathbf{e}_i \, d\mathbf{y}.$$

But we are not comfortable with applying this to our situation :

- the plate has only a small number K of layers of cells and this technique disregards the boundary layers
- The plate thickness converges to 0 as $\varepsilon \rightarrow 0$.

These weaknesses can be overcome by :

- replacing the unit cell with a cell column : $Y = [0, 1]^2 \times [0, K]$;
- looking for a plate model (2D model) with solution $u(x_1, x_2)$.

We thus modify the expansion :

$$u_\varepsilon(x) = u_0(\bar{x}, y) + \varepsilon u_1(x, y) + \varepsilon^2 u_2(x, y) + \dots$$

where $\bar{x} = (x_1, x_2)$, $\bar{y} = \bar{x}/\varepsilon$. Again, this gives that $u_0(\bar{x}, y) = u(\bar{x}) = u(x_1, x_2)$ and that u is solution of

$$\left\{ \begin{array}{l} -\operatorname{div}_x (A^* \nabla_x u) = Kf \quad \text{in } \Omega^*, \end{array} \right. \quad (0.4)$$

where $\Omega = \Omega^* \times [0, K]$ and A^* has a form similar to the previous one.

- **Remarks :**

In the case of a domain with holes (a lattice!), the homogenized problem takes the form

$$\left\{ \begin{array}{l} -\operatorname{div}_{\mathbf{x}} (A^* \nabla_{\mathbf{x}} u) + \theta u = \theta K f \quad \text{in } \Omega^*, \end{array} \right. \quad (0.5)$$

where θ is the volumic fraction occupied by the solid material.

- **What could be done next :**

- extend the present study to shell-like lattice structure and to the elasticity system ;
- litterature review on the modelling of plate-like and shell-like lattice structures.
- Compare numerically the proposed homogenized plate and shell models with the starting models.