

Critical behavior in non-intersecting path ensembles

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Based on joint works with
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Outline

1. Introduction

- ▲ OP ensembles and non-intersecting path ensembles
- ▲ Multiple orthogonal polynomials (MOPs) and MOP ensembles
- ▲ Riemann-Hilbert problem for MOPs

2. Non-intersecting Brownian motions

- ▲ One starting position, two ending positions
- ▲ Two starting positions, two ending positions
- ▲ Critical separation and Painlevé II
- ▲ Brief outline of steepest descent analysis

3. Non-intersecting squared Bessel paths

- ▲ MOP ensemble with modified Bessel weights
- ▲ Global and local regimes
- ▲ Critical time and new family of kernels

Part 1: Introduction

- ▲ The structure behind eigenvalues of unitary random matrices appears in other situations as well
 - ▲ Non-intersecting paths
 - ▲ Tiling problems, stochastic growth problems
 - ▲ Representation theory of large groups
- ▲ They are **determinantal point processes**: a random point process so that correlation functions have determinantal form

$$\det [K(x_j, x_k)]_{j,k=1,\dots,m}$$

- ▲ K is the correlation kernel

OP ensembles

- ▲ The eigenvalues from a unitary random matrix ensemble

$$\frac{1}{Z_n} \exp(-\text{Tr } V(M)) dM$$

defined on $n \times n$ **Hermitian matrices** M follow a determinantal point process with correlation kernel

$$K(x, y) = \sqrt{e^{-V(x)}} \sqrt{e^{-V(y)}} \sum_{j=0}^{n-1} p_j(x) p_j(y)$$

- ▲ p_j is the orthonormal polynomial of degree j with weight $e^{-V(x)}$
- ▲ **Orthogonal Polynomial ensemble**

Non-intersecting path ensembles

- ▲ Given n independent copies $X_1(t), \dots, X_n(t)$ of a 1-D strong Markov process with continuous sample paths, conditioned to
 - ▲ start at time $t = 0$ at n given points $a_1 < a_2 < \dots < a_n$,
 - ▲ end at time $t = 1$ at n given points $b_1 < b_2 < \dots < b_n$,
 - ▲ **not intersect** in the full time interval $(0, 1)$.
- ▲ Then the positions of the paths at given time $t \in (0, 1)$ are a determinantal point process.
 - ▲ Consequence of **Karlin-McGregor (1959)** theorem.

Correlation kernel

- ▲ If $p_t(x, y)$ is the Markov process transition p.d.f., then by Karlin-McGregor theorem, the p.d.f. for the positions x_1, \dots, x_n of the paths at time t is

$$\frac{1}{Z_n} \det [p_t(a_j, x_k)]_{j,k=1,\dots,n} \cdot \det [p_{1-t}(x_k, b_j)]_{j,k=1,\dots,n}$$

- ▲ The correlation kernel K takes the form

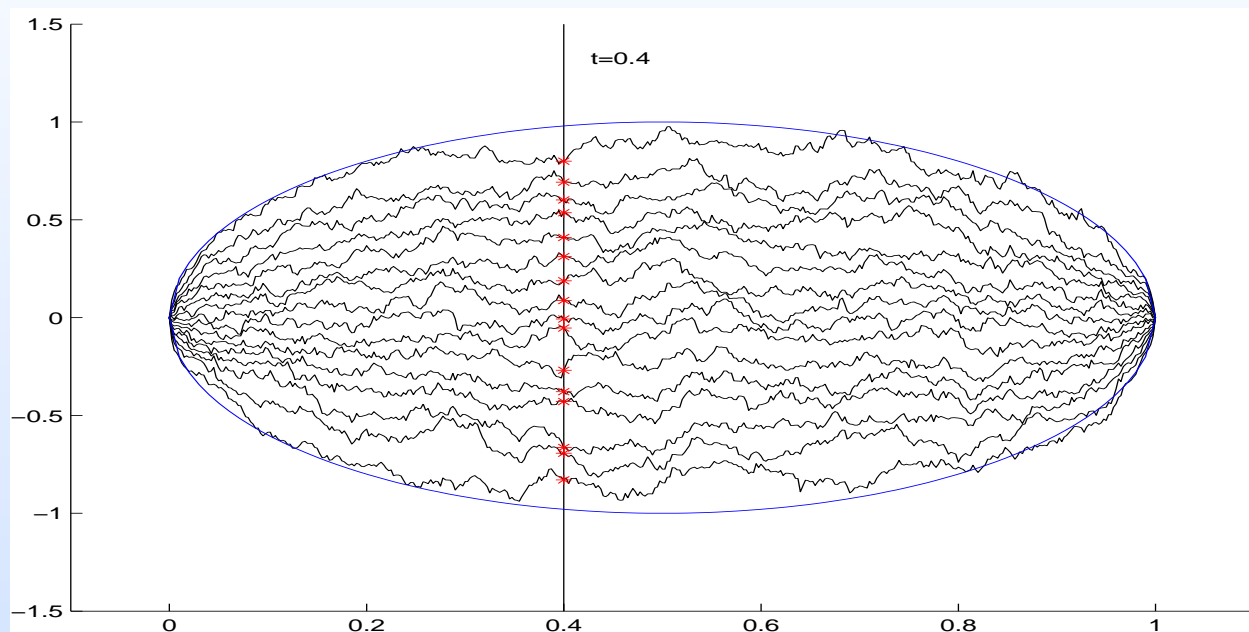
$$K(x, y) = \sum_{j=1}^n \phi_j(x) \psi_j(y)$$

where **biorthogonal functions** ϕ_j and ψ_j arise from biorthogonalizing the two sets of functions $x \mapsto p_t(a_j, x)$ and $x \mapsto p_{1-t}(x, b_j)$

$$\int \phi_j(x) \psi_k(x) dx = \delta_{j,k}$$

Confluent Brownian motion case as a model for GUE

- ▲ The **confluent case** $a_j \rightarrow 0, b_j \rightarrow 0$, for Brownian motion leads to (a variation of) Dyson's Brownian motion



Biorthogonal ensemble

- ▲ OP ensembles and non-intersecting path ensembles are examples of **biorthogonal ensembles**

$$\mathcal{P}(x_1, \dots, x_n) = \frac{1}{Z_n} \det [f_j(x_k)]_{j,k=1,\dots,n} \cdot \det [g_j(x_k)]_{j,k=1,\dots,n}$$

for given functions f_1, \dots, f_n , and g_1, \dots, g_n .

- ▲ A biorthogonal ensemble has a correlation kernel

$$K_n(x, y) = \sum_{j=1}^n \phi_j(x) \psi_j(y) \quad \text{where}$$

- ▲ ϕ_1, \dots, ϕ_n is a basis for $\text{span}\{f_1, \dots, f_n\}$
- ▲ ψ_1, \dots, ψ_n is a basis for $\text{span}\{g_1, \dots, g_n\}$
- ▲ $\int \phi_j(x) \psi_k(x) dx = \delta_{j,k}$ (**biorthogonality**)

Multiple Orthogonal Polynomial ensembles

▲ If $f_j(x) = x^{j-1}w_1(x)$ and $g_j(x) = x^{j-1}w_2(x)$, then **OP ensemble**.

▲ **MOP ensemble if**

f_j 's are: $x^{j-1}w_{1,k}(x)$, for $j = 1, \dots, n_k$, $k = 1, \dots, p$,

g_j 's are: $x^{j-1}w_{2,k}(x)$, for $j = 1, \dots, m_k$, $k = 1, \dots, q$,

with $\sum n_k = \sum m_k$.

▲ **Biorthogonal functions take the form**

$$\phi_j(x) = \sum_{k=1}^p A_{j,k}(x)w_{1,k}(x), \quad \psi_j(x) = \sum_{k=1}^q B_{j,k}(x)w_{2,k}(x)$$

with $\sum_k \deg A_{j,k} = \sum_k \deg B_{j,k} = j - 1$.

▲ We call $A_{j,k}$ and $B_{j,k}$ **multiple orthogonal polynomials** ($p + q$ **MOPs**).

Riemann-Hilbert problem for 1 + 2 MOPs

- ▲ MOPs (with 1 + 2 weights) satisfy a 3×3 matrix valued RH problem

Van Assche-Geronimo-Kuijlaars (2001)

generalization of Fokas-Its-Kitaev (1992) RH problem for OPs

- ▲ $Y : \mathbb{C} \setminus \mathbb{R} \rightarrow \mathbb{C}^{3 \times 3}$ is analytic

- ▲ $Y_+(x) = Y_-(x) \begin{pmatrix} 1 & w_{1,1}(x)w_{2,1}(x) & w_{1,1}(x)w_{2,2}(x) \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \quad x \in \mathbb{R}$

- ▲ $Y(z) = (I_3 + \mathcal{O}(1/z)) \begin{pmatrix} z^{n_1} & 0 & 0 \\ 0 & z^{-m_1} & 0 \\ 0 & 0 & z^{-m_2} \end{pmatrix}$ as $z \rightarrow \infty$

(recall $n_1 = m_1 + m_2$)

- ▲ The correlation kernel for the MOP ensemble is given in terms of the solution Y of the RH problem

$$K(x, y) = \frac{1}{2\pi i(x-y)} \begin{pmatrix} 0 & w_{2,1}(y) & w_{2,2}(y) \end{pmatrix} Y_+(y)^{-1} Y_+(x) \begin{pmatrix} w_{1,1}(x) \\ 0 \\ 0 \end{pmatrix}$$

Bleher-Kuijlaars (2004), Daems-Kuijlaars (2004)

Riemann-Hilbert problem for $2 + 2$ MOPs

- ▲ $p + q$ MOPs satisfy a $(p + q) \times (p + q)$ **matrix valued** RH problem

stated here for the $2 + 2$ case

Daems-Kuijlaars (2007)

- ▲ $Y : \mathbb{C} \setminus \mathbb{R} \rightarrow \mathbb{C}^{4 \times 4}$ is analytic

- ▲ $Y_+(x) = Y_-(x) \begin{pmatrix} I & W(x) \\ 0 & I \end{pmatrix}$, for $x \in \mathbb{R}$ where

$$W(x) = \begin{pmatrix} w_{1,1}(x) \\ w_{1,2}(x) \end{pmatrix} \begin{pmatrix} w_{2,1}(x) & w_{2,2}(x) \end{pmatrix}$$

- ▲ $Y(z) = (I_4 + \mathcal{O}(1/z)) \text{diag}(z^{n_1}, z^{n_2}, z^{-m_1}, z^{-m_2})$ as $z \rightarrow \infty$

- ▲ The correlation kernel for the MOP ensemble is

$$K(x, y) = \frac{1}{2\pi i(x - y)} \begin{pmatrix} 0 & 0 & w_{2,1}(y) & w_{2,2}(y) \end{pmatrix} Y_+(y)^{-1} Y_+(x) \begin{pmatrix} w_{1,1}(x) \\ w_{1,2}(x) \\ 0 \\ 0 \end{pmatrix}$$

Part 2: Non intersecting Brownian paths

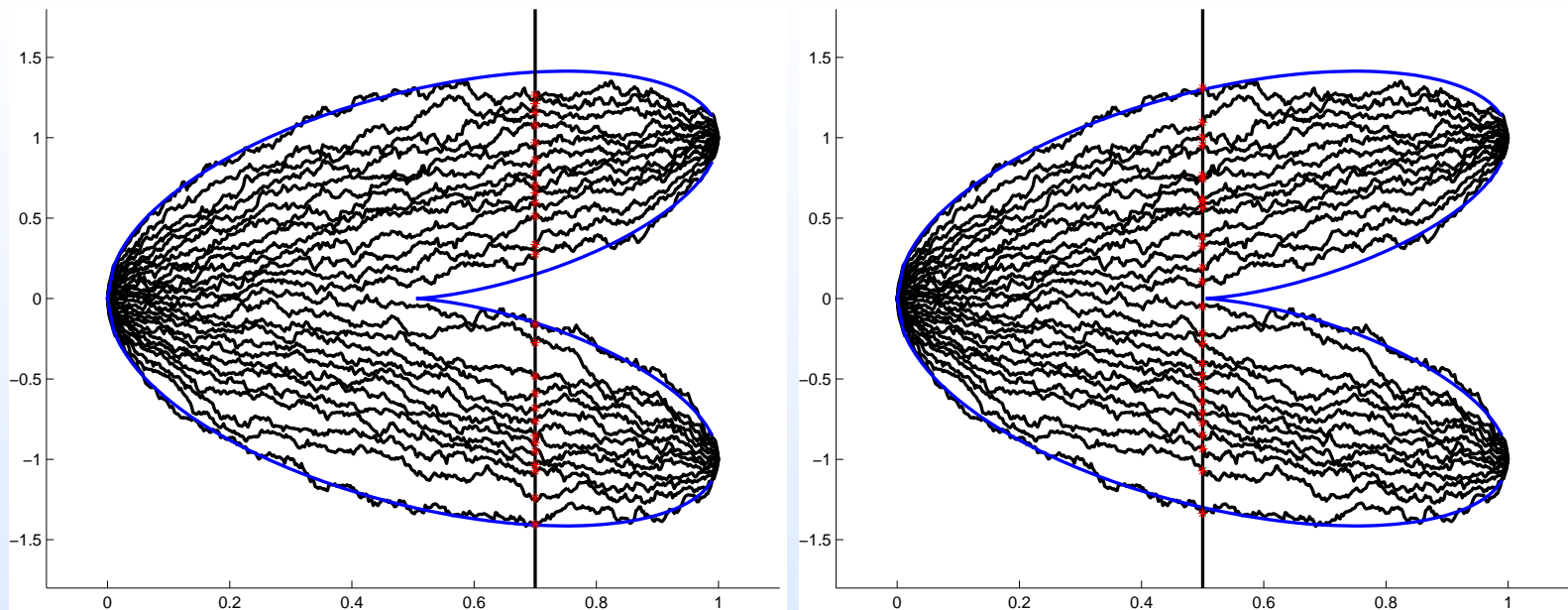
- ▲ Take n non-intersecting Brownian motions so that
 - ▲ p starting points a_1, \dots, a_p and q ending points b_1, \dots, b_q
 - ▲ n_k paths start at a_k and m_k paths end at b_k
- ▲ The positions of the paths at time $t \in (0, 1)$ are MOP ensemble with $p + q$ weights

$$w_{1,k}(x) = e^{-\frac{(x-a_k)^2}{2t}}, \quad k = 1, \dots, p,$$

$$w_{2,k}(x) = e^{-\frac{(x-b_k)^2}{2(1-t)}}, \quad k = 1, \dots, q.$$

- ▲ MOPs in this case are called **multiple Hermite polynomials**

One starting position, two ending positions



▲ Asymptotic analysis of the 3×3 matrix valued RH problem

(Aptekarev)-Bleher-Kuijlaars (2004, 2005, 2007), McLaughlin (2007), Orantin (arXiv)

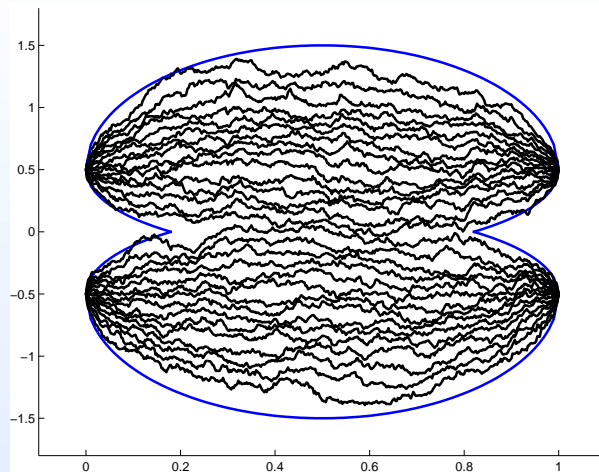
▲ Usual scaling limits from random matrix theory are found in the bulk
(**sine kernel**) and at the edges (**Airy kernel**)

▲ Double scaling limit at the **cusp point**: a family of **Pearcey kernels**

Brézin-Hikami (1998), Tracy-Widom (2006), Okounkov-Reshetikhin (2007)

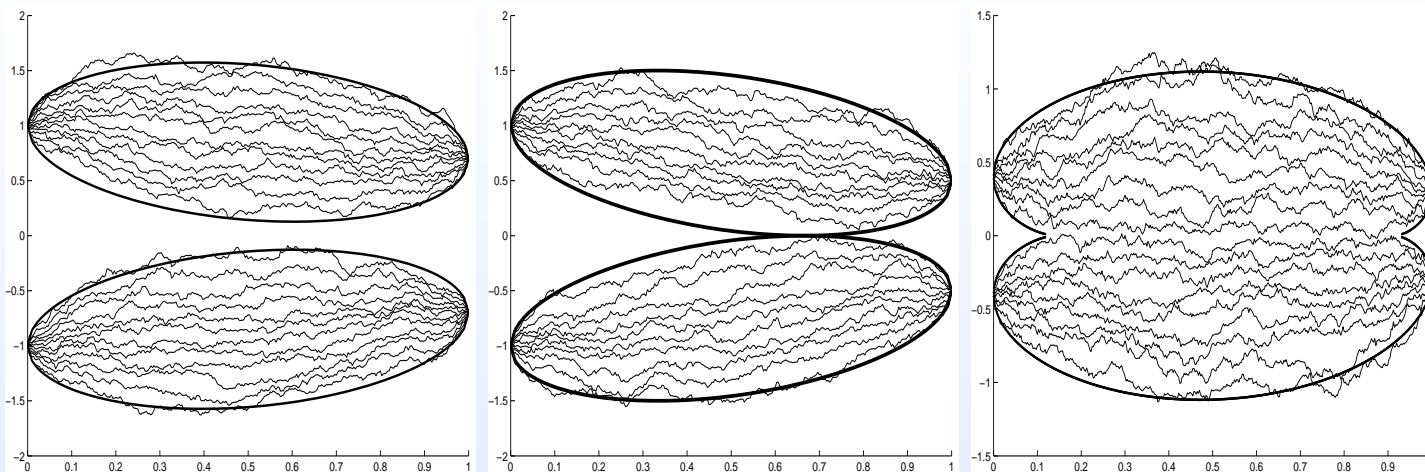
Adler-van Moerbeke (2007), Bleher-Kuijlaars (2007)

Two starting positions, two ending positions



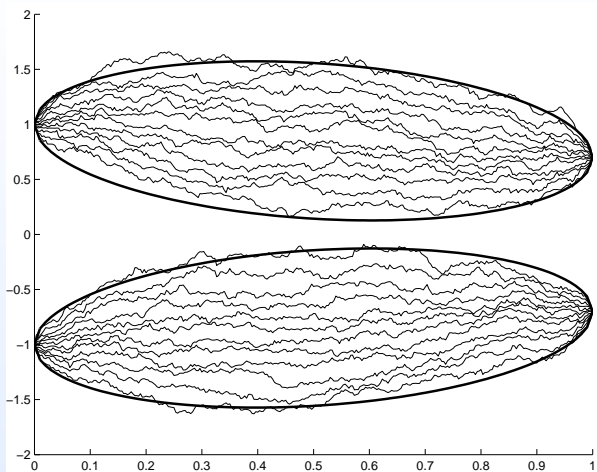
- ▲ **Asymptotic analysis of 4×4 matrix valued RH problem for case $n_1 = n_2 = m_1 = m_2$ and small separation** Daems-Kuijlaars-Veys (2008)
 - ▲ The paths fill out an algebraic curve of degree six
 - ▲ Sine kernel in the bulk and Airy kernel at the edges
 - ▲ Pearcey kernels at the cusp points is expected (we did not prove it)

Critical separation



- ▲ If $n_1 = m_1$ and $n_2 = m_2$ there is a phase transition at critical separation
 - ▲ At critical separation the paths fill out two tangent ellipses.
 - ▲ At larger separation the two ellipses are disjoint.
 - ▲ At smaller separation the paths fill out one simply connected domain bounded by an algebraic curve.

Large separation



- ▲ Take $n_1 = m_1$, $n_2 = m_2$,
- ▲ $\frac{n_1}{n} = p_1$, $\frac{n_2}{n} = p_2 = 1 - p_1$,
- ▲ $a_1 > a_2$, $b_1 > b_2$.
- ▲ When separation between initial and ending positions is large enough, one expects two disjoint ellipses.

- ▲ Paths at time t are on $[\alpha_2(t), \beta_2(t)] \cup [\alpha_1(t), \beta_1(t)]$ where

$$\alpha_j(t) = (1-t)a_j + tb_j - 2\sqrt{p_j t(1-t)}$$

$$\beta_j(t) = (1-t)a_j + tb_j + 2\sqrt{p_j t(1-t)}$$

- ▲ Ellipses are disjoint if $\beta_2(t) < \alpha_1(t)$ for all $t \in (0, 1)$, and this happens if and only if

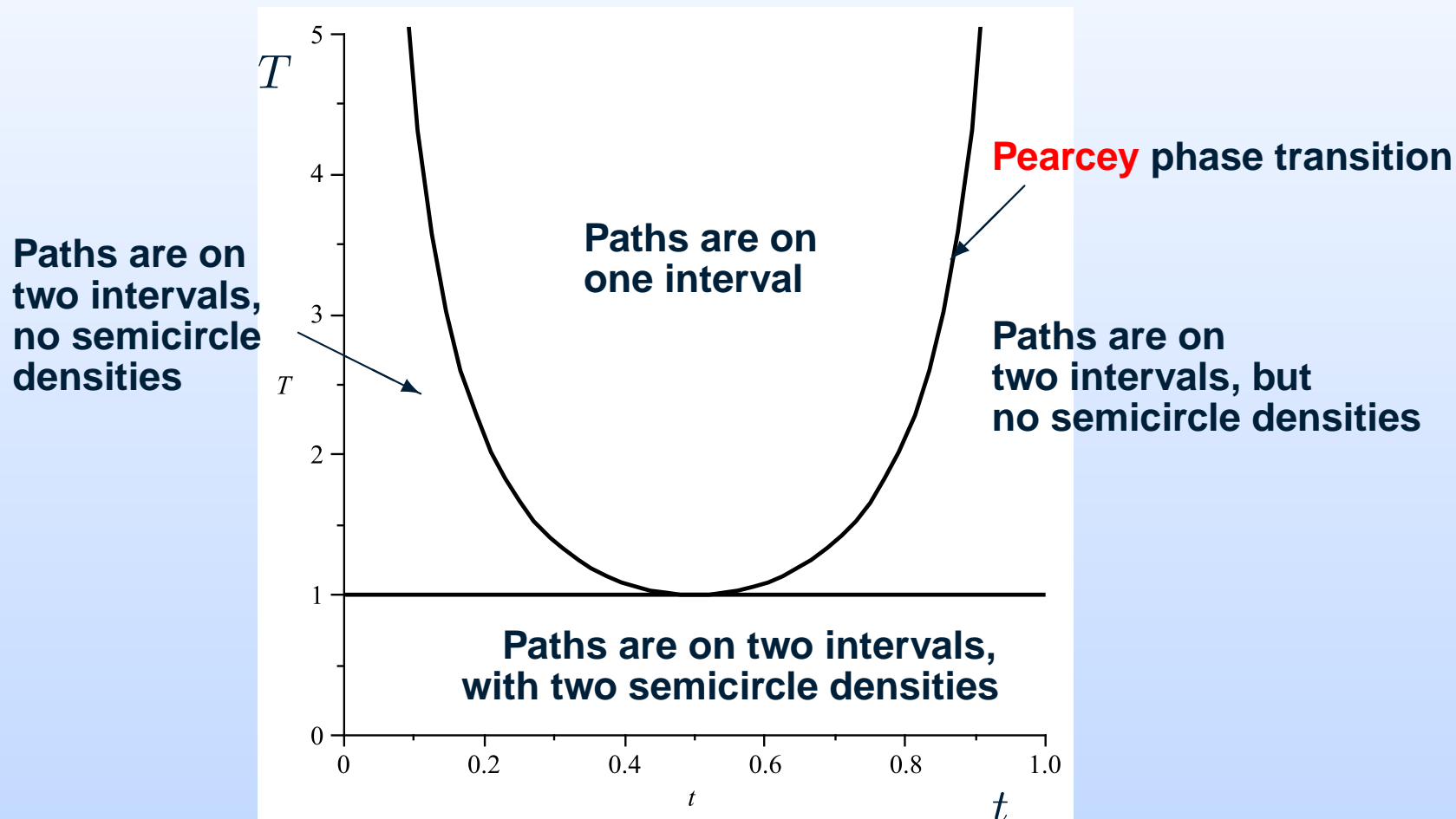
$$(a_1 - a_2)(b_1 - b_2) > (\sqrt{p_1} + \sqrt{p_2})^2$$

Phase diagram

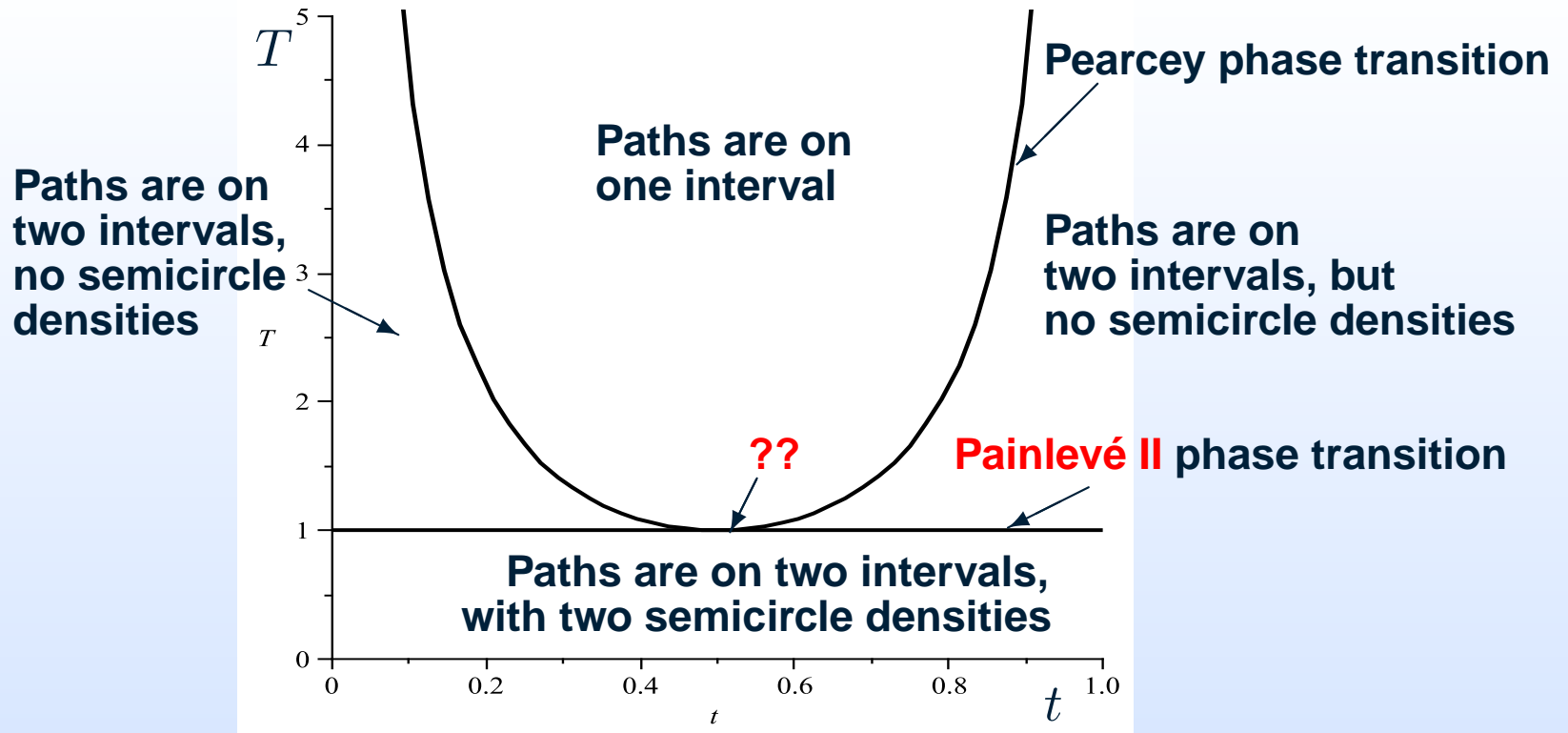
- ▲ **Brownian motion transition probability** $\sqrt{\frac{n}{2\pi tT}} \exp\left(-\frac{n}{T} \frac{(x-y)^2}{2t}\right)$
- ▲ **Take** $(a_1 - a_2)(b_1 - b_2) = (\sqrt{p_1} + \sqrt{p_2})^2$: **critical separation if** $T = 1$.

Phase diagram

- ▲ **Brownian motion transition probability** $\sqrt{\frac{n}{2\pi tT}} \exp\left(-\frac{n}{T} \frac{(x-y)^2}{2t}\right)$
- ▲ **Take** $(a_1 - a_2)(b_1 - b_2) = (\sqrt{p_1} + \sqrt{p_2})^2$: **critical separation if** $T = 1$.



Phase diagram: Painlevé II transition at $T = 1$



- ▲ The transition at $T = 1$ at the **non-critical time** is governed by the **Hastings-McLeod solution** of the **Painlevé II equation**
- ▲ There are no new scaling limits of the correlation kernel, but the Hastings-McLeod solution is seen in the asymptotics of the **recurrence coefficients** of the multiple Hermite polynomials

Delvaux-Kuijlaars

Outline of proof

- ▲ **Asymptotic analysis of 4×4 matrix valued RH problem with jump condition**

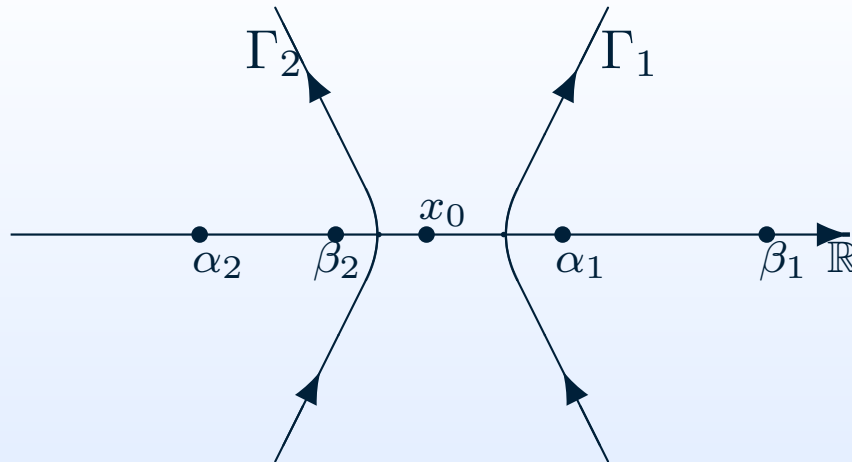
$$Y_+(x) = Y_-(x) \begin{pmatrix} I & W(x) \\ 0 & I \end{pmatrix}, \quad \text{for } x \in \mathbb{R},$$

where $W(x) = \begin{pmatrix} w_{1,1}(x) \\ w_{1,2}(x) \end{pmatrix} \begin{pmatrix} w_{2,1}(x) & w_{2,2}(x) \end{pmatrix}$ **with**

$$w_{1,k}(x) = \exp\left(-\frac{n}{T} \frac{(x - a_k)^2}{2t}\right), \quad w_{2,k}(x) = \exp\left(-\frac{n}{T} \frac{(x - b_k)^2}{2(1-t)}\right), \quad k = 1, 2,$$

- ▲ **Direct application of g -functions corresponding to semi-circle laws fails.**
- ▲ **First we do a global preliminary transformation (“global opening of lenses”)**

Preliminary transformation



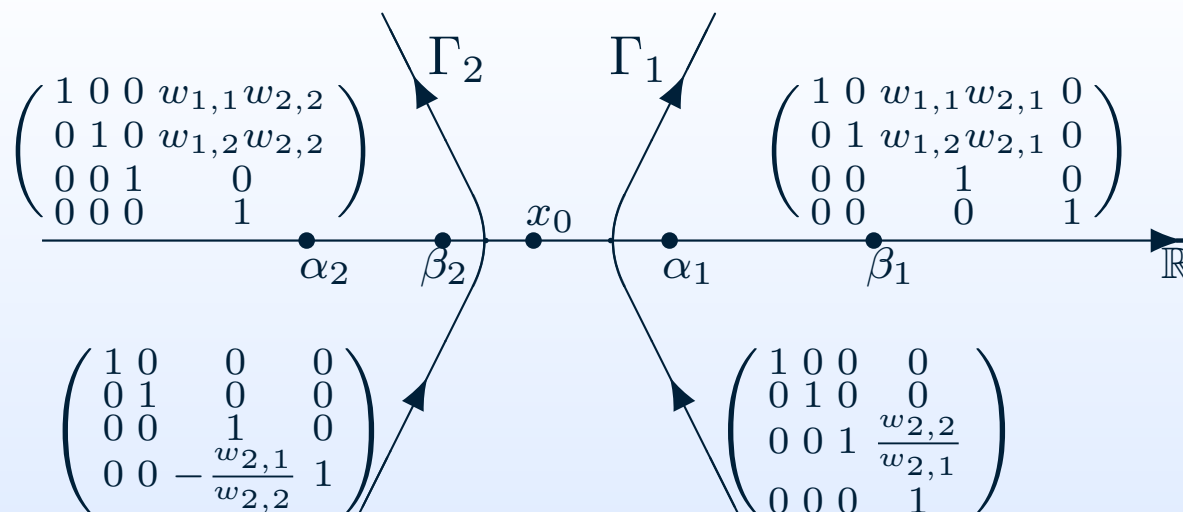
▲ Assume **small time** $t < t_{cr}$, and define

$$X = Y \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & -\frac{w_{2,2}}{w_{2,1}} \\ 0 & 0 & 0 & 1 \end{pmatrix} \quad \text{to the right of } \Gamma_1,$$

$$X = Y \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & -\frac{w_{2,1}}{w_{2,2}} & 1 \end{pmatrix} \quad \text{to the left of } \Gamma_2,$$

$$X = Y \quad \text{elsewhere.}$$

Jumps in the RH problem for X



▲ Now we define

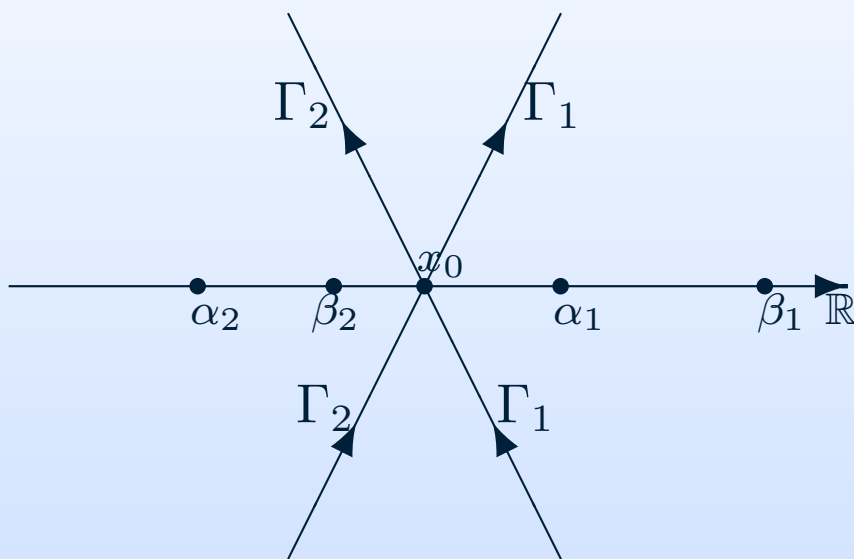
$$T = L^{-n} X G^n L^n$$

where L is a constant diagonal matrix, $G = \text{diag}(e^{-g_1}, e^{-g_2}, e^{g_1}, e^{g_2})$.

▲ If we are in a situation of **large separation**, i.e., $T < 1$, then we can take Γ_1 and Γ_2 so that jumps on these contours tend to identity matrix as $n \rightarrow \infty$ at an exponential rate.

Critical separation

- ▲ It does not work in the case of **critical separation**, i.e., $T = 1$.
- ▲ Then the best we can do is to let Γ_1 and Γ_2 meet in a point $x_0 \in (\beta_2, \alpha_1)$.
- ▲ Away from x_0 the jumps are exponentially close to the identity matrix.



- ▲ A **local parametrix** at x_0 is constructed with the help of the RH problem for the Hastings-McLeod solution of Painlevé II

$$q'' = sq + 2q^3$$

Baik-Deift-Johansson (1999), Bleher-Its (2003), Claeys-Kuijlaars (2006)

Part 3: Squared Bessel process

- ▲ **Squared Bessel process** is a strong Markov process on $[0, \infty)$ depending on a parameter $\alpha > -1$, with transition probabilities

$$p_t^\alpha(x, y) = \frac{1}{2t} \left(\frac{y}{x}\right)^{\alpha/2} e^{-(x+y)/(2t)} I_\alpha\left(\frac{\sqrt{xy}}{t}\right), \quad x, y > 0,$$

where I_α is the **modified Bessel function** of the first kind of order α

$$I_\alpha(z) = \sum_{k=0}^{\infty} \frac{(z/2)^{2k+\alpha}}{k! \Gamma(k + \alpha + 1)}$$

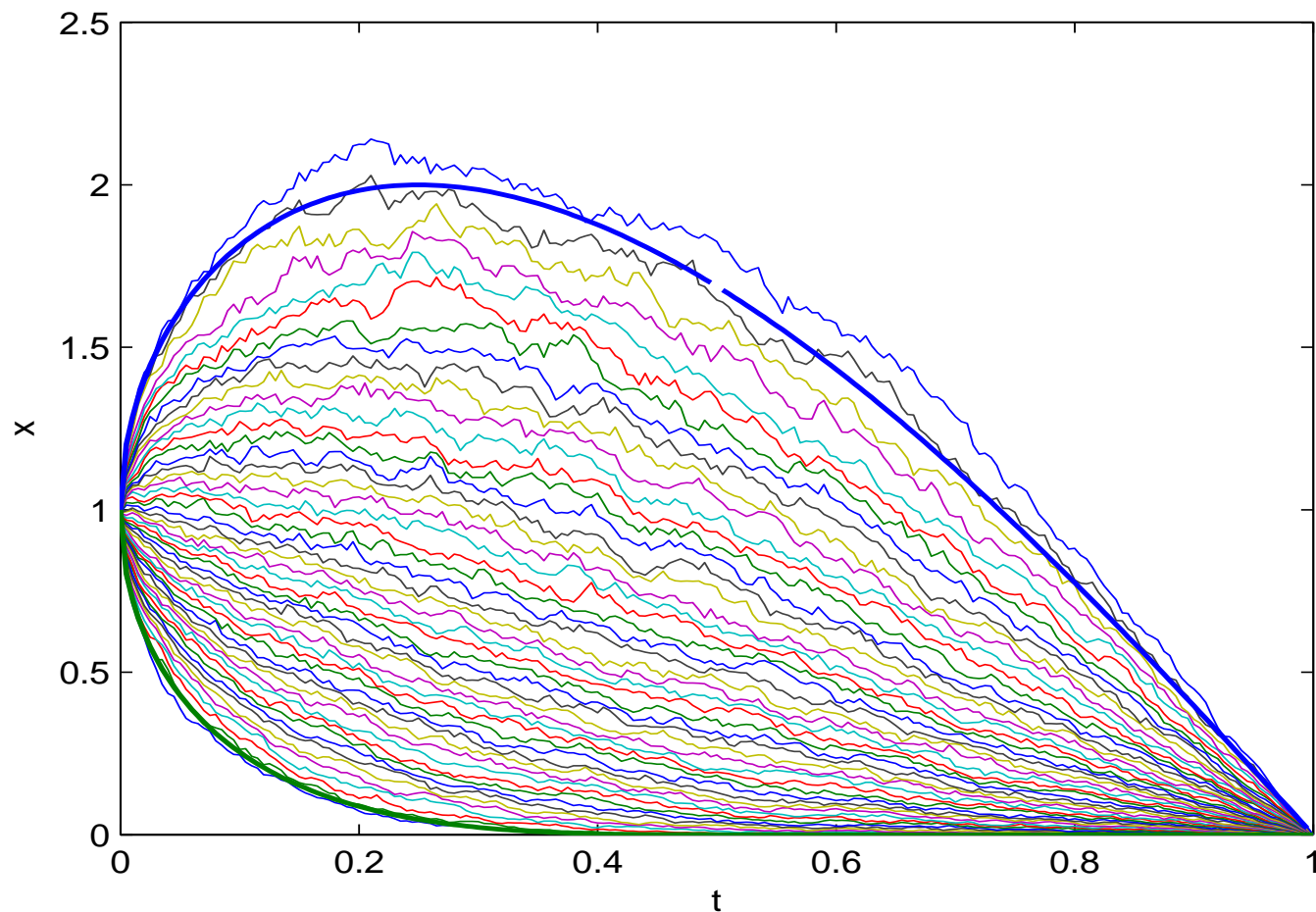
- ▲ If $d = 2(\alpha + 1)$ is an integer, then the squared Bessel process is the square of the distance to the origin of a d -dimensional Brownian motion.
 - ▲ Non-intersecting squared Bessel processes were considered by **König-O'Connell (2001)**, **Katori-Tanemura (2007)**, and **Desrosiers-Forrester (2008)**. Related work by **Tracy-Widom (2007)** on non-intersecting Brownian excursions.

Simulation of 50 non-intersecting paths

▲ **Confluent case:** **all** $a_j \rightarrow a > 0$, **all** $b_j \rightarrow 0$.

Simulation of 50 non-intersecting paths

▲ **Confluent case:** all $a_j \rightarrow a > 0$, all $b_j \rightarrow 0$.



Non-intersecting squared Bessel paths

- ▲ In confluent limit $a_j \rightarrow a$, $b_j \rightarrow 0$, the positions of n non-intersecting squared Bessel paths at time $t \in (0, 1)$ are a **MOP ensemble** with $1 + 2$ weight functions

$$w_{1,1}(x) = e^{-\frac{x}{2(1-t)}}, \quad n_1 = n,$$

$$w_{2,1}(x) = x^{\alpha/2} e^{-\frac{x}{2t}} I_{\alpha} \left(\frac{\sqrt{ax}}{t} \right), \quad m_1 := \lceil n/2 \rceil,$$

$$w_{2,2}(x) = x^{(\alpha+1)/2} e^{-\frac{x}{2t}} I_{\alpha+1} \left(\frac{\sqrt{ax}}{t} \right), \quad m_2 := \lfloor n/2 \rfloor.$$

- ▲ Proof depends on differential equations for modified Bessel functions
- ▲ Corollary: correlation kernel is expressible in terms of solution of RH problem with jump condition for $x > 0$,

$$Y_+(x) = Y_-(x) \begin{pmatrix} 1 & x^{\alpha/2} e^{-\frac{x}{t(1-t)}} I_{\alpha} \left(\frac{\sqrt{ax}}{t} \right) & x^{(\alpha+1)/2} e^{-\frac{x}{t(1-t)}} I_{\alpha+1} \left(\frac{\sqrt{ax}}{t} \right) \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}.$$

Rescaling and ODE

▲ To obtain non-trivial limits as $n \rightarrow \infty$, we rescale $a \mapsto na$, $x \mapsto nx$.

▲ Rescaled weights

$$w_{1,1}(x)w_{2,1}(x) = x^{\alpha/2} e^{-\frac{nx}{t(1-t)}} I_{\alpha} \left(n \frac{\sqrt{ax}}{t} \right),$$

$$w_{1,1}(x)w_{2,2}(x) = x^{(\alpha+1)/2} e^{-\frac{nx}{t(1-t)}} I_{\alpha+1} \left(n \frac{\sqrt{ax}}{t} \right).$$

▲ MOPs with modified Bessel weights were studied in two papers by [Coussement-Van Assche \(2003\)](#). They found a third order ODE for them, which in the rescaled variables is

$$\begin{aligned} & xy'''(x) + \left((2 + \alpha) - \frac{2nx}{t(1-t)} \right) y''(x) \\ & + \left(\frac{n^2x}{t^2(1-t)^2} + \frac{n(n-\alpha-2)}{t(1-t)} - \frac{an^2}{t^2} \right) y'(x) - \frac{n^3}{t^2(1-t)^2} y(x) = 0 \end{aligned}$$

Asymptotics

- ▲ **Formal WKB analysis of the ODE (as $n \rightarrow \infty$) leads to algebraic equation**

$$x\zeta^3 - \frac{2x}{t(1-t)}\zeta^2 + \left(\frac{x}{t^2(1-t)^2} + \frac{1}{t(1-t)} - \frac{a}{t^2} \right)\zeta - \frac{1}{t^2(1-t)^2} = 0$$

- ▲ **The equation has branch points $x_-(t) < x_+(t)$ and 0.**

- ▲ **There is a **critical time** $t_{cr} = \frac{a}{a+1}$ so that**

- ▲ **For $0 < t < t_{cr}$ we have $0 < x_-(t) < x_+(t)$**

- ▲ **For $t_{cr} < t < 1$ we have $x_-(t) < 0 < x_+(t)$**

- ▲ **Asymptotic analysis of RH problem confirms that paths accumulate on $[\max(0, x_-(t)), x_+(t)]$ with limiting mean density**

$$\frac{d\mu(x)}{dx} = \frac{1}{\pi} |\operatorname{Im} \zeta(x)|$$

- ▲ **For $t \neq t_{cr}$ we also find usual scaling limits: **sine kernel**, **Airy kernel** and **Bessel kernel** [Kuijlaars-Martinez Finkelshtein-Wielonsky \(arxiv 2007, to appear in CMP\)](#)**

Local regime at critical time

▲ **Double scaling limit at $x^* = 0$ and $t = t_{cr}$:**

$$\lim_{n \rightarrow \infty} \frac{1}{cn^{3/2}} K_n \left(\frac{x}{cn^{3/2}}, \frac{y}{cn^{3/2}}; t = t_{cr} + \frac{\tau}{c'n^3} \right) = ??$$

leads to new family of kernels depending on parameter τ

Local regime at critical time

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$$\lim_{n \rightarrow \infty} \frac{1}{cn^{3/2}} K_n \left(\frac{x}{cn^{3/2}}, \frac{y}{cn^{3/2}}; t = t_{cr} + \frac{\tau}{c'n^3} \right) = ??$$

leads to new family of kernels depending on parameter τ

- ▲ Limiting kernels involve a special solution of **third order ODE**

$$x f''' + (2 + \alpha) f'' - \tau f' - f = 0$$

which is the double scaling limit of the ODE for MOPs, and its adjoint

$$-(yg)''' + (\alpha + 2)g'' + \tau g' - g = 0$$

Local regime at critical time

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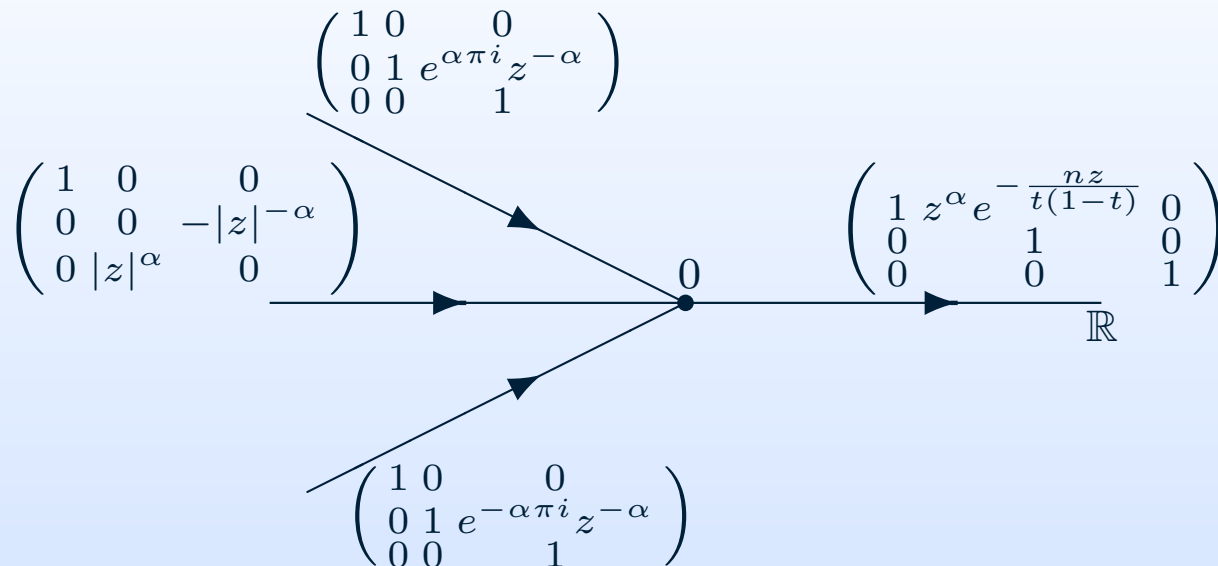
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$$-(yg)''' + (\alpha + 2)g'' + \tau g' - g = 0$$

$$\frac{1}{\pi(x-y)} [f(x)(yg(y))'' - f'(x)(2g(y) + yg'(y)) \\ + f''(x)yg(y) - (\alpha + 2)f(x)g'(y) - \tau f(x)g(y)]$$

Steps in steepest descent analysis

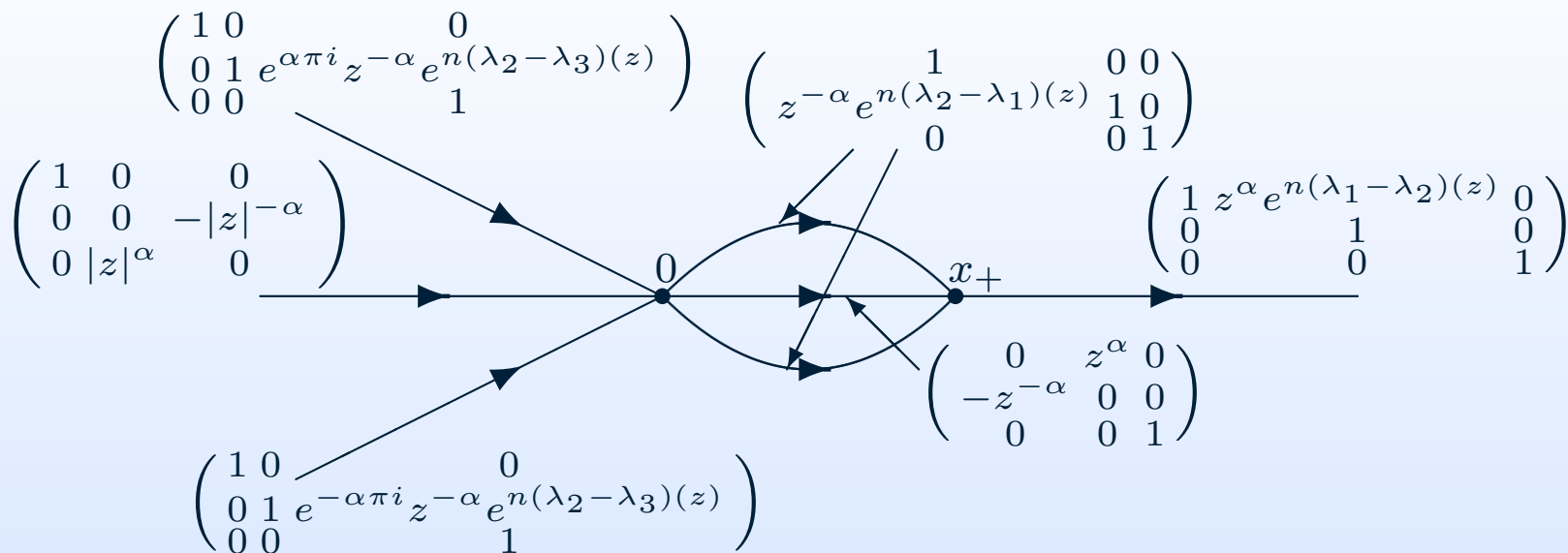
- ▲ Initial RH problem for Y has jump on $[0, \infty)$.
- ▲ First preliminary step $Y \mapsto X$ introduces jump on negative real line



$$K_n(x, y) = \frac{1}{2\pi i(x-y)} \begin{pmatrix} 0 & y^\alpha e^{-\frac{ny}{t(1-t)}} & 0 \end{pmatrix} X_+^{-1}(y) X_+(x) \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}.$$

Next steps in steepest descent analysis

- ▲ Application of g -functions $X \mapsto U$ and opening of lenses $U \mapsto T$



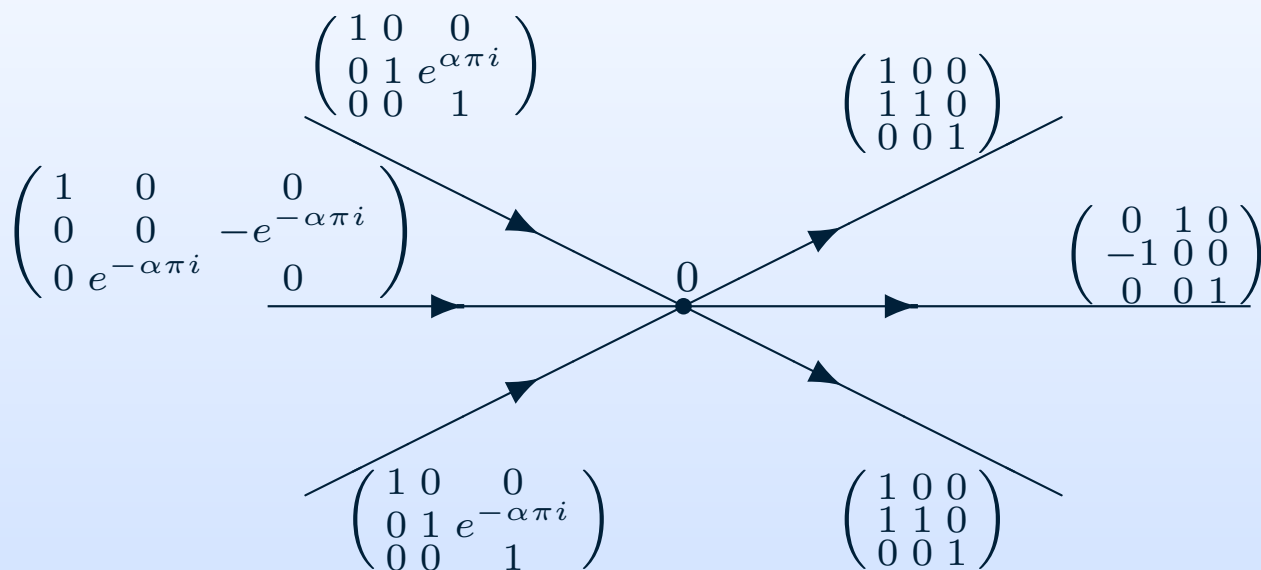
- ▲ The $\lambda_j(z)$'s are anti-derivatives of the solutions $\zeta_j(z)$ of the algebraic equation

$$K_n(x, y) = \frac{1}{2\pi i(x - y)} \begin{pmatrix} -e^{-n\lambda_{1,+}(y)} & y^\alpha e^{-n\lambda_{2,+}(y)} & 0 \end{pmatrix} T_+^{-1}(y) T_+(x) \begin{pmatrix} e^{n\lambda_{1,+}(x)} \\ x^{-\alpha} e^{n\lambda_{2,+}(x)} \\ 0 \end{pmatrix}$$

Reduction to constant jumps

▲ Reduction to constant jumps near 0 (magnified picture)

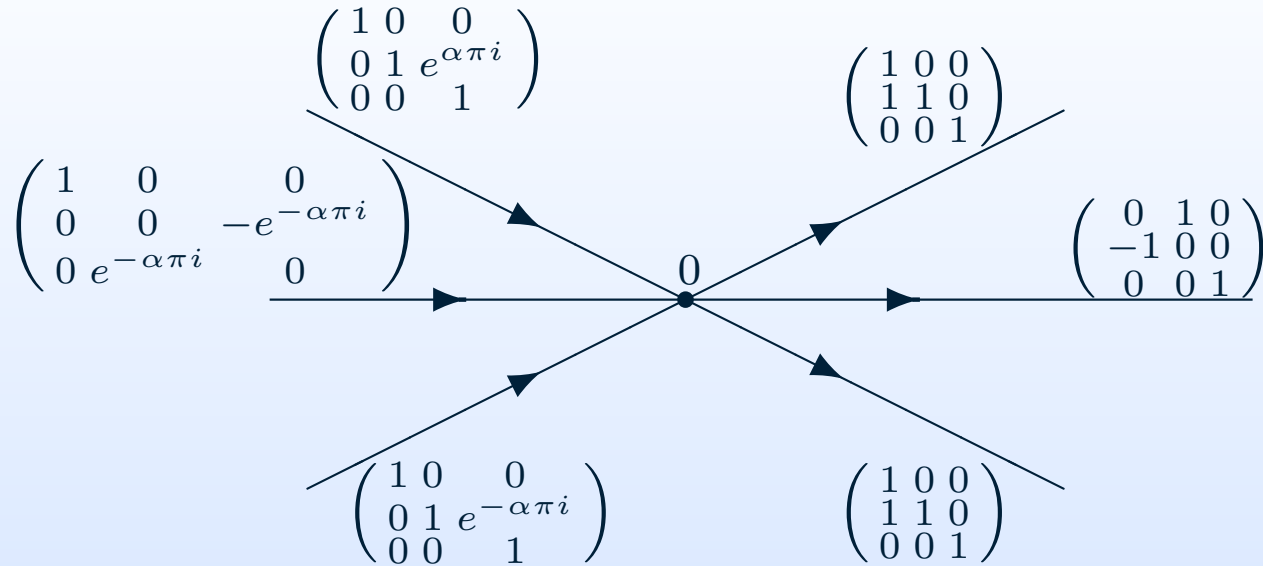
$$S(z) = T(z) \operatorname{diag} \left(e^{n\lambda_1(z)} \quad z^{-\alpha} e^{n\lambda_2(z)} \quad e^{n\lambda_3(z)} \right)$$



$$K_n(x, y) = \frac{1}{2\pi i(x-y)} \begin{pmatrix} -1 & 1 & 0 \end{pmatrix} S_+^{-1}(y) S_+(x) \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$$

Parametrix at 0

- ▲ We look for model solution Ψ with jumps on infinite rays



- ▲ Limiting kernel is

$$\frac{1}{2\pi i(x-y)} \begin{pmatrix} -1 & 1 & 0 \end{pmatrix} \Psi_+^{-1}(y) \Psi_+(x) \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$$

Solution Ψ

▲ We construct Ψ from solutions of $xf''' + (\alpha + 2)f'' - \tau f' - f = 0$.

▲ There are solutions of the form

$$f(x) = \int_{\Gamma} t^{\alpha-1} e^{\tau/t} e^{1/(2t^2)} e^{xt} dt$$

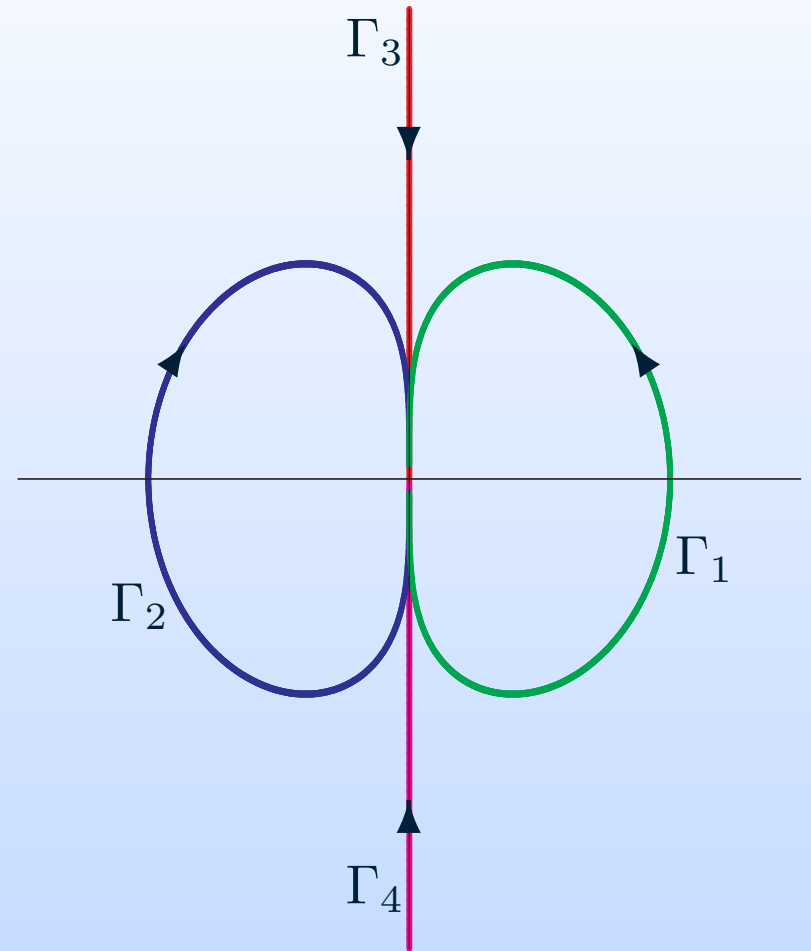
where Γ connects $0 + i0, 0 - i0, \infty$.

$$f_1(x) = \frac{1}{2\pi i} \int_{\Gamma_1} \dots$$

$$f_2(x) = \frac{e^{-\alpha\pi i}}{2\pi i} \int_{\Gamma_2} \dots$$

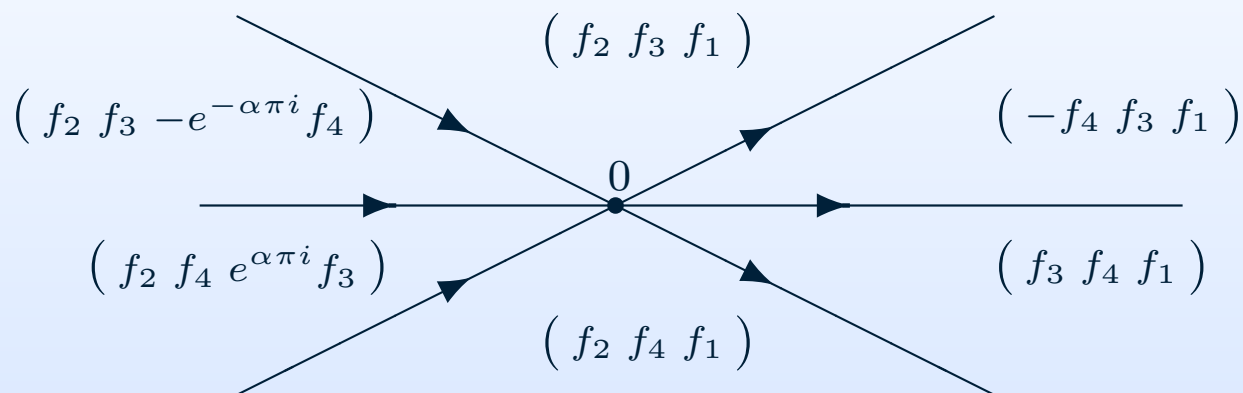
$$f_3(x) = \frac{e^{-\alpha\pi i}}{2\pi i} \int_{\Gamma_3} \dots$$

$$f_4(x) = \frac{e^{\alpha\pi i}}{2\pi i} \int_{\Gamma_4} \dots$$



Jumps are satisfied

- ▲ Choose right combination of solutions in each sector so that the jump conditions are satisfied (+ an asymptotic condition ...)



- ▲ Other rows of Ψ contain derivatives.
- ▲ The special solution that appears in the limiting kernel is

$$-f_4(x) + f_3(x) = f_2(x) = \frac{e^{-\alpha\pi i}}{2\pi i} \int_{\Gamma_2} t^{\alpha-1} e^{\tau/t} e^{1/(2t^2)} e^{xt} dt$$

- ▲ The inverse Ψ^{-1} contains solutions of the adjoint equation