

Progress in the classification of second order superintegrable systems

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- ① What is a superintegrable system
- ② Nondegenerate second order superintegrability in 2D
- ③ Conformal superintegrability and a geometric definition of superintegrability
- ④ Towards a classification in nD

Classical integrability

- $2n$ -dimensional phase space with coordinates (\mathbf{x}, \mathbf{p})
- Hamiltonian

$$H = g + V = \sum_{i,j=1}^n g^{ij}(\mathbf{x}) p_i p_j + V(\mathbf{x}).$$

- Poisson bracket $\{ , \}$
- Hamilton's equations

$$\dot{p}_i = -\frac{\partial H}{\partial x_i}, \quad \dot{x}_i = \frac{\partial H}{\partial p_i}$$

- $L(\mathbf{x}, \mathbf{p})$ such that $\{H, L\} = 0$ is an integral or symmetry.
- n mutually commuting integrals $H = L_1, L_i(\mathbf{x}, \mathbf{p})$,

$$\{L_i, L_j\} = 0, \quad i, j = 1 \dots n.$$

Classical superintegrability

- $2n$ -dimensional phase space with coordinates $(\mathbf{x}, \mathbf{p}) = (x_i, p_i)$
- Hamiltonian

$$H = \sum_{i,j=1}^n g^{ij}(\mathbf{x}) p_i p_j + V(\mathbf{x}).$$

- More than n integrals $H = L_1, L_i(x_i, p_i),$

$$\{L_i, L_j\} = 0, \quad i = 1 \dots 2n - 1.$$

- **Maximally superintegrable** systems have $2n - 1$ independent integrals.
- Trajectories lie in 1D submanifolds.

- n -dimensional manifold with coordinates $\mathbf{x} = (x_1, \dots, x_n)$
- Hamiltonian

$$H = \Delta + V(\mathbf{x}),$$

- Integrable: n algebraically independent differential operators H, L_i such that

$$[H, L_i] = 0, \quad [L_i, L_j] = 0, \quad \text{for all } i, j = 1, \dots, n-1.$$

- The L_i are symmetries.
- Superintegrable: H has $2n - 1$ independent symmetries
- Associated with the possibility of solving the eigenvalue problem $H\Psi = E\Psi$ exactly, analytically and algebraically.

- Also known as *degenerate integrability* or *non-Abelian integrability*.
- Symmetries form a non-trivial algebra (eg Racah algebra).
- Second order superintegrability leads to multiseparability and interesting connections with orthogonal polynomials.
- Inönü-Wigner and Bôcher contractions of 2D second order superintegrable systems reproduce the Askey-Wilson scheme of orthogonal polynomials.

Example: Kepler

The Kepler Hamiltonian in **3** dimensions is

$$H = p_x^2 + p_y^2 + p_z^2 + \frac{\alpha}{r}, \quad r = \sqrt{x^2 + y^2 + z^2}$$

with $\{H, M_i\} = \{H, L_i\} = 0$ for $i = 1, 2, 3$, where

$$M_1 = yp_z - zp_y, \quad L_1 = p_y M_3 - p_z M_2 + \frac{\alpha x}{2r},$$

$$M_2 = zp_x - xp_z, \quad L_2 = p_z M_1 - p_x M_3 + \frac{\alpha y}{2r},$$

$$M_3 = xp_y - yp_x, \quad L_3 = p_x M_2 - p_y M_1 + \frac{\alpha z}{2r}.$$

H is maximally superintegrable due to Laplace-Runge-Lenz vector.

At most $2 \times \mathbf{3} - 1 = 5$ constants can be functionally independent.

$$M_1 L_1 + M_2 L_2 + M_3 L_3 = 0 \quad \text{and} \quad L_1^2 + L_2^2 + L_3^2 - (M_1^2 + M_2^2 + M_3^2)H = \frac{\alpha^2}{4}.$$

The symmetry algebra closes quadratically.

$$\{M_i, M_j\} = \epsilon_{ijk} M_k, \quad \{L_i, M_j\} = \epsilon_{ijk} L_k \quad \text{and} \quad \{L_i, L_j\} = \epsilon_{ijk} H M_k.$$

Example: Deformations of Kepler

A 4 parameter (semi-degenerate) deformation of Kepler is also superintegrable with **second order constants**:

$$H = p_x^2 + p_y^2 + p_z^2 + \frac{\alpha}{r} + \frac{\beta}{x^2} + \frac{\gamma}{y^2} + \delta.$$

A 5 parameter (non-degenerate) deformation of Kepler is also superintegrable but requires a **fourth order constant** (Verrier & Evans 2008):

$$H = p_x^2 + p_y^2 + p_z^2 + \frac{\alpha}{r} + \frac{\beta}{x^2} + \frac{\gamma}{y^2} + \frac{\delta}{z^2} + \eta.$$

The symmetry algebras of these systems close polynomially but only if an additional functionally dependent symmetry is included.

These have quantum counter parts.

Example: Smorodinsky-Winternitz system (1965)

$$H = p_x^2 + p_y^2 + \alpha(x^2 + y^2) + \frac{\beta}{x^2} + \frac{\gamma}{y^2} + \delta$$

$$L_1 = p_x^2 + \alpha x^2 + \frac{\beta}{x^2}, \quad L_2 = (x p_y - y p_x)^2 + \beta \frac{y^2}{x^2} + \gamma \frac{x^2}{y^2}.$$

$$\{H, L_1\} = \{H, L_2\} = 0.$$

With $R = \{L_1, L_2\}$ the Poisson algebra closes quadratically.

$$\{R, L_1\} = 8L_1^2 - 8(H - \delta)L_1 + 16\alpha L_2,$$

$$\{R, L_2\} = -16L_1L_2 + 8(H - \delta)L_2 - 16(\beta + \gamma)L_1 + 16(H - \delta)\beta,$$

$$R^2 = -16L_1^2L_2 + 16(H - \delta)L_1L_2 - 16\alpha L_2^2 - 16(\beta + \gamma)L_2^2 \\ + 32\beta(H - \delta)L_1 - 16\beta(H - \delta)^2 + 16\alpha\beta\gamma.$$

- Oscillators with rational frequency ratios

$$H = \frac{1}{2}(p_x^2 + p_y^2) + \omega_1^2 x^2 + \omega_2^2 y^2, \quad \frac{\omega_1}{\omega_2} \in \mathbb{Q}$$

- Calogero-Moser (Wojciechowski, 1983)

$$H = \frac{1}{2} \sum_{i=1}^n p_i^2 + \sum_{i < j=1}^n \frac{1}{(x_i - x_j)^2}$$

- Toda lattice (non-polynomial symmetries) (Agrotis, Damianou, Sophocleous, 2005)

$$H = \frac{1}{2} \sum_{i=1}^n p_i^2 + \sum_{i=1}^{n-1} e^{x_i - x_{i+1}}$$

- A non-separable system (Post and Winternitz, 2011)

$$H = \frac{1}{2}(p_x^2 + p_y^2) + \frac{\alpha y}{x^{2/3}}$$

This talk: **second order superintegrability**

- 2D free systems ($V = 0$) found by Koenigs (1872).
- 2D non-degenerate¹ systems are known.
- 2D degenerate systems are parameter restrictions of non-degenerate systems.
- 3D non-degenerate systems on conformally flat spaces are known.
- 3D degenerate systems — examples are known.²
- nD — examples are known.

Quadratically closed symmetry algebras exist in all dimensions.

¹Potentials depending on the maximum number of parameters - see later.

²Miller and Escobar Ruiz 2017 — large family of semi-degenerate systems

2D complex Euclidean second order systems

Consider 2D complex Euclidean space with complex variables

$$z = x + iy, \quad \bar{z} = x - iy, \quad p_z = \frac{1}{2}(p_x - ip_y), \quad p_{\bar{z}} = \frac{1}{2}(p_x + ip_y),$$

and look for Hamiltonians of the form

$$H = 4p_z p_{\bar{z}} + V(z, \bar{z})$$

admitting two independent second order constants

$$\begin{aligned} L_1 &= a_1^{(1)} p_z^2 + a_2^{(1)} p_z p_{\bar{z}} + a_3^{(1)} p_{\bar{z}}^2 + W^{(1)} \\ L_2 &= a_1^{(2)} p_z^2 + a_2^{(2)} p_z p_{\bar{z}} + a_3^{(2)} p_{\bar{z}}^2 + W^{(2)}, \end{aligned}$$

where $a_j^{(i)}$ and $W^{(i)}$ are functions of z and \bar{z} .

An immediate consequence of

$$\{H, L_1\} = \{H, L_2\} = 0$$

is that the $a_j^{(1)}$ and $a_j^{(2)}$ are the components of a Killing tensor.

Nondegenerate systems

Integrability conditions for $W^{(i)}$ (Bertrand-Darboux equations) are:

$$-2a_1^{(1)}V_{zz} + 2a_3^{(1)}V_{\bar{z}\bar{z}} = \left(a_{2\bar{z}}^{(1)} - 2a_{1z}^{(1)}\right)V_z - \left(a_{2z}^{(1)} - 2a_{3\bar{z}}^{(1)}\right)V_{\bar{z}},$$

$$-2a_1^{(2)}V_{zz} + 2a_3^{(2)}V_{\bar{z}\bar{z}} = \left(a_{2\bar{z}}^{(2)} - 2a_{1z}^{(2)}\right)V_z - \left(a_{2z}^{(2)} - 2a_{3\bar{z}}^{(2)}\right)V_{\bar{z}}.$$

Solve for V_{zz} and $V_{\bar{z}\bar{z}}$ in terms of $V_{z\bar{z}}$, V_z and $V_{\bar{z}}$.

$$\begin{bmatrix} V_{zz} \\ V_{\bar{z}\bar{z}} \end{bmatrix} = \begin{bmatrix} C^{11} & C^{12} \\ C^{21} & C^{22} \end{bmatrix} \begin{bmatrix} V_z \\ V_{\bar{z}} \end{bmatrix}$$

Nondegenerate: all derivatives of V at \mathbf{x}_0 are determined by the 4 parameters $V_{z\bar{z}}(\mathbf{x}_0)$, $V_z(\mathbf{x}_0)$, $V_{\bar{z}}(\mathbf{x}_0)$ and $V(\mathbf{x}_0)$.

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Solve for V_{zz} and $V_{\bar{z}\bar{z}}$ in terms of $V_{z\bar{z}}$, V_z and $V_{\bar{z}}$.

$$\begin{bmatrix} V_{zz} \\ V_{\bar{z}\bar{z}} \end{bmatrix} = \begin{bmatrix} C^{11} & C^{12} \\ C^{21} & C^{22} \end{bmatrix} \begin{bmatrix} V_z \\ V_{\bar{z}} \end{bmatrix}$$

Nondegenerate: all derivatives of V at \mathbf{x}_0 are determined by the 4 parameters $V_{z\bar{z}}(\mathbf{x}_0)$, $V_z(\mathbf{x}_0)$, $V_{\bar{z}}(\mathbf{x}_0)$ and $V(\mathbf{x}_0)$.

Integrability of $a_j^{(i)}$

For each constant

$$L = a_1^{(i)} p_z^2 + a_2^{(i)} p_z p_{\bar{z}} + a_3^{(i)} p_{\bar{z}}^2 + W,$$

coefficients of cubic terms in $\{H, L\} = 0$ and integrability conditions for W lead to

$$\partial_z a_1^{(i)} = -\frac{2}{3} C^{11} a_1^{(i)} + \frac{2}{3} C^{21} a_3^{(i)}$$

$$\partial_{\bar{z}} a_1^{(i)} = 0$$

$$\partial_z a_2^{(i)} = \frac{2}{3} C^{22} a_3^{(i)} - \frac{2}{3} C^{12} a_1^{(i)}$$

$$\partial_{\bar{z}} a_2^{(i)} = \frac{2}{3} C^{11} a_1^{(i)} - \frac{2}{3} C^{21} a_3^{(i)}$$

$$\partial_z a_3^{(i)} = 0$$

$$\partial_{\bar{z}} a_3^{(i)} = -\frac{2}{3} C^{22} a_3^{(i)} + \frac{2}{3} C^{12} a_1^{(i)}$$

All derivatives of the $a_j^{(i)}$ at a point are determined by their values and the $C^{k\ell}$ at that point.

[Greatly simplified prolongation of Killing tensor equations.]

Integrability for $a_j^{(i)}$ give expressions for derivatives of the C^{ij} .

With two new symbols $C_z^{21} = \partial_z C^{21}$ and $C_{\bar{z}}^{12} = \partial_{\bar{z}} C^{12}$ we have

$$\begin{aligned}
 \partial_z C^{11} &= \frac{2}{3} C^{22} C^{12} + \frac{2}{3} (C^{11})^2 - C_{\bar{z}}^{12} & \partial_{\bar{z}} C^{11} &= \frac{2}{3} C^{12} C^{21} \\
 \partial_z C^{22} &= \frac{2}{3} C^{12} C^{21} & \partial_{\bar{z}} C^{22} &= \frac{2}{3} C^{11} C^{21} + \frac{2}{3} (C^{22})^2 - C_z^{21} \\
 \partial_z C^{12} &= \frac{2}{3} C^{11} C^{12} & \partial_{\bar{z}} C^{21} &= \frac{2}{3} C^{22} C^{21} \\
 \partial_z C_z^{21} &= \frac{2}{3} C_z^{21} C^{22} + \frac{4}{9} C^{12} C^{21} & \partial_z C_{\bar{z}}^{12} &= \frac{2}{3} C_{\bar{z}}^{12} C^{11} + \frac{4}{9} C^{12} C^{21} \\
 \\ \\
 \partial_z C_z^{21} &= \frac{8}{9} C^{22} C^{12} C^{21} - \frac{4}{3} C^{21} C_{\bar{z}}^{12} + \frac{4}{9} C^{21} (C^{11})^2 + \frac{2}{3} C^{11} C_z^{21} \\
 \partial_{\bar{z}} C_{\bar{z}}^{12} &= \frac{8}{9} C^{11} C^{12} C^{21} - \frac{4}{3} C^{12} C_z^{21} + \frac{4}{9} C^{12} (C^{22})^2 + \frac{2}{3} C^{22} C_{\bar{z}}^{12}.
 \end{aligned}$$

Integrability conditions are:

$$0 = 9C^{21}C_{\bar{z}}^{12} - 3C^{11}C_z^{21} - 2C^{22}C^{12}C^{21} - 2C^{21}(C^{11})^2$$

$$0 = 9C^{12}C_z^{21} - 3C^{22}C_{\bar{z}}^{12} - 2C^{11}C^{12}C^{21} - 2C^{12}(C^{22})^2$$

$$0 = 9C_{\bar{z}}^{12}C_z^{21} - 3C^{11}C^{21}C_{\bar{z}}^{12} - 3C^{22}C^{12}C_z^{21} + (C^{12})^2(C^{21})^2 \\ - 2C^{11}C^{22}C^{12}C^{21}$$

Define some numbers a_{ij} by

$$D = \det \begin{bmatrix} a_{(1)}^1 & a_{(2)}^1 \\ a_{(1)}^3 & a_{(2)}^3 \end{bmatrix} = \sum a_{ij} z^i \bar{z}^j$$
$$A_z = a_{21} \bar{z}^2 + 2a_{20} \bar{z} + a_{30}$$
$$B_{\bar{z}} = a_{12} z^2 + 2a_{02} z + a_{03}.$$

Then

$$\begin{bmatrix} V_{zz} \\ V_{z\bar{z}} \end{bmatrix} = \begin{bmatrix} C^{11} & C^{12} \\ C^{21} & C^{22} \end{bmatrix} \begin{bmatrix} V_z \\ V_{\bar{z}} \end{bmatrix} = \frac{1}{D} \begin{bmatrix} -D_z & A_z \\ B_{\bar{z}} & -D_{\bar{z}} \end{bmatrix}$$

The integrability conditions require that D factors as

$$D(z, \bar{z}) = (a_1 z + c_1)(a_2 z + b_2 \bar{z} + c_2)(b_3 \bar{z} + c_3)$$

or

$$D(z, \bar{z}) = (a_1 z + b_1 \bar{z} + c_1)(a_3 z + b_3 \bar{z} + c_3).$$

2D second order superintegrable systems

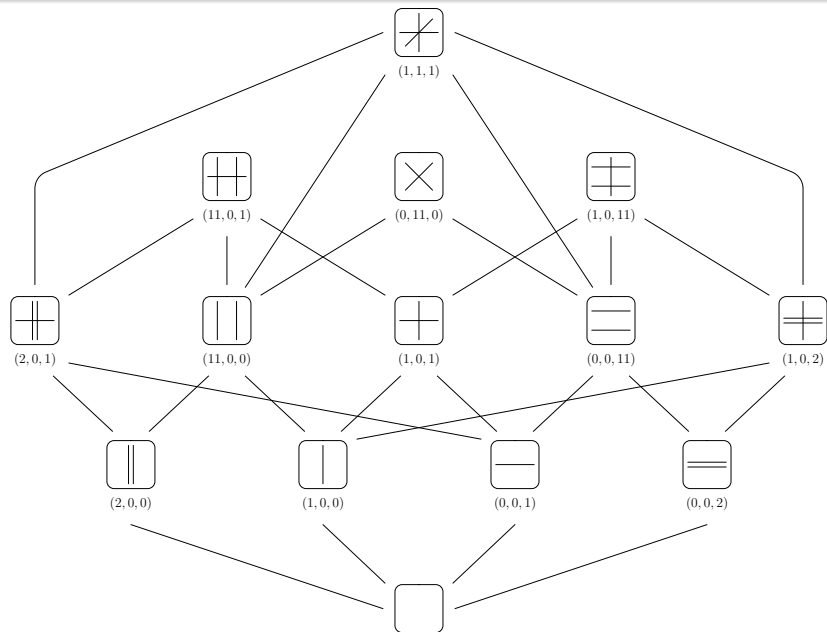
class	$D(z, \bar{z})$	superintegrable potentials		
(1, 1, 1)	$z(z + \bar{z})\bar{z}$	$\frac{1}{\sqrt{z\bar{z}}}$	$\frac{1}{\sqrt{z\bar{z}}} \frac{1}{(\sqrt{z} + \sqrt{\bar{z}})^2}$	$\frac{1}{\sqrt{z\bar{z}}} \frac{1}{(\sqrt{z} - \sqrt{\bar{z}})^2}$
(11, 0, 1)	$z(z + 1)\bar{z}$	$\frac{\bar{z}}{\sqrt{(\bar{z}+1)(\bar{z}-1)}}$	$\frac{1}{\sqrt{z(\bar{z}+1)}}$	$\frac{1}{\sqrt{z(\bar{z}-1)}}$
(2, 0, 1)	$z^2\bar{z}$	$\frac{1}{\sqrt{z\bar{z}}}$	$\frac{1}{\bar{z}\sqrt{z\bar{z}}}$	$\frac{1}{\bar{z}^2}$
(0, 11, 0)	$(z + \bar{z})(z - \bar{z})$	$z\bar{z}$	$\frac{1}{x^2}$	$\frac{1}{y^2}$
(11, 0, 0)	$z(z + 1)$	$z\bar{z}$	$\frac{\bar{z}}{\sqrt{\bar{z}^2 - 1}}$	$\frac{2z\bar{z}^2 - z}{\sqrt{\bar{z}^2 - 1}}$
(2, 0, 0)	z^2	$z\bar{z}$	$\frac{1}{\bar{z}^2}$	$\frac{z}{\bar{z}^3}$
(1, 0, 1)	$z\bar{z}$	$\frac{1}{\sqrt{z\bar{z}}}$	$\frac{1}{\sqrt{z}}$	$\frac{1}{\sqrt{\bar{z}}}$

2D second order superintegrable systems

class	$D(z, \bar{z})$	superintegrable potentials		
$(0, 1, 0)$	$z + \bar{z}$	$x^2 + 4y^2$	$\frac{1}{x^2}$	y
$(1, 0, 0)$	z	$\frac{z}{\sqrt{\bar{z}}}$	$\frac{1}{\sqrt{\bar{z}}}$	z
$(1, 0, 0)$	z	$\frac{1}{\sqrt{\bar{z}}}$	x	$\frac{z+3\bar{z}}{\sqrt{\bar{z}}}$
$(0, 0, 0)$	1	$z\bar{z}$	z	\bar{z}
$(0, 0, 0)$	1	$\bar{z}^3 + 3z\bar{z}$	$\bar{z}^2 + z$	\bar{z}

K and Schöbel: arXiv:1602.07890

2D second order superintegrable systems



Conformally superintegrable systems

A maximally **conformally superintegrable** Hamiltonian

$$H = \sum_{i,j=1}^n g^{ij}(\mathbf{x}) p_i p_j + V(\mathbf{x}),$$

has $2n - 1$ functionally independent **conformal constants** (polynomial in p_i) that commute with H up to a multiple of H ,

$$\{H, L\} = \rho_L H,$$

where ρ_L a polynomial in p_i .

[Conformally commuting = R -commuting.]

L is constant on the hypersurface $H = 0$.

Superintegrable systems are conformally superintegrable with all $\rho_L = 0$.

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Coupling constant metamorphosis (Stäckel transform)

Suppose

$$H = H_0 + \alpha V \quad \text{and} \quad L = L_0 + \alpha W \quad \text{with} \quad \{H, L\} = \rho_L H.$$

Then coupling constant metamorphosis (Stäckel transform) gives

$$L' = L_0 - WH' \quad \text{and} \quad H' = \frac{H_0}{V} \quad \Rightarrow \quad \{H', L'\} = 0.$$

L_1 and L_2 are conformal constants for H with $\{L_1, L_2\} = \rho_{12} H$

↓ CCM

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conformally superintegrable system

CCM
→

superintegrable system

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CCM
→

superintegrable system

Superintegrable integral \Rightarrow conformally SI on flat space

A superintegrable system on a conformally flat space can be written as

$$H = \frac{1}{\lambda} \sum_{i=1}^n p_i^2 + V.$$

Suppose L is a constant for H , that is,

$$\{H, L\} = 0.$$

If we define

$$\hat{H} = \sum_{i=1}^n p_i^2 + \lambda V$$

then

$$\{\hat{H}, L\} = \rho \hat{H}$$

where $\rho = \lambda^{-1} \{\lambda, L\}$.

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A more geometric perspective

One-to-one correspondence:

superintegrable systems on conformally flat spaces



conformally superintegrable systems on flat space

A different perspective. Think of the potential V as a family of conformal scalings.

A non-degenerate superintegrable system is a subspace of second rank Killing tensors that remains Killing under a family of conformal scalings.

Algebraic superintegrability conditions in nD

Consider a second order maximally superintegrable system.

$$H = g + V = \sum \frac{1}{2} g_{ij}^{(\alpha)}(\mathbf{x}) p^i p^j + V$$

admitting $2n - 1$ functionally independent constants

$$L^{(\alpha)} = K^{(\alpha)} + V^{(\alpha)}, \quad \alpha = 1 \dots 2n - 2,$$

where

$$K^{(\alpha)}(\mathbf{x}, \mathbf{p}) = \sum \frac{1}{2} K_{ij}^{(\alpha)}(\mathbf{x}) p^i p^j$$

Imposing

$$0 = \{H, L^{(\alpha)}\} = \{g + V, K + V^{(\alpha)}\} = \{g, K\} + \{g, V^{(\alpha)}\} + \{V, K\}$$

requires

$$\{g, K\} = 0 \quad (\text{Killing tensor equation})$$

$$\{g, V^{(\alpha)}\} + \{V, K\} = 0 \quad (*)$$

(*) is $dV^{(\alpha)} = K^{(\alpha)}dV$ and has integrability condition

$$d(K^{(\alpha)}dV) = 0 \quad (\text{Bertrand-Darboux})$$

With equations from $2n - 1$ linearly independent integrals and “solve” the Bertrand-Darboux equations to obtain.

$$\nabla_i \nabla_j V = T_{ij}{}^m \nabla_m V + \frac{1}{n} g_{ij} \Delta V$$

- $T_{ij}{}^k$ is determined by Killing tensor subspace.
- Higher derivatives of V are determined by ∇V and ΔV .
- If no further conditions relate ∇V and ΔV then V is **non-degenerate** and depends on $n + 2$ parameters.

Prologation of superintegrable Killing tensor

- Substituting

$$\nabla_i \nabla_j V = T_{ij}{}^m \nabla_m V + \frac{1}{n} g_{ij} \Delta V$$

- into

$$d(KdV) = 0$$

gives

$$K_{ij,k} = \frac{1}{3} \begin{array}{|c|c|} \hline j & i \\ \hline k & \\ \hline \end{array} T^m{}_{ji} K_{mk}.$$

This is a miraculously short prologation.

($\begin{array}{|c|c|} \hline j & i \\ \hline k & \\ \hline \end{array}$ is a symmetriser that symmetrises on indices in rows and antisymmetrises on indices in columns.)

Prologation of Killing tensor (Wolf '98)

$$K_{ab;c}^0 = K_{abc}^1$$

$$K_{abc;d}^1 = K_{abcd}^2 + S_{ab} (K_{am}^0 R^m_{bcd})$$

$$\begin{aligned} K_{abcd;e}^2 = & 2 S_{ab} (S_{cde} (K_{cm}^0 R^m_{bda;e} - K_{cm}^0 R^m_{dea;b} + \\ & 2 K_{acm}^1 R^m_{deb} - K_{cdm}^1 R^m_{bea}) \\ & + S_{cd} (\frac{1}{3} K_{am}^0 R^m_{cdb;e} + \frac{2}{3} K_{am}^0 R^m_{ecb;d} - \\ & \frac{1}{3} K_{abm}^1 R^m_{dec} + 2 K_{amc}^1 R^m_{edb} - \\ & K_{ame}^1 R^m_{cdb})) \end{aligned}$$

Prologation of Killing tensor (Wolf '98)

$$\begin{aligned}
 0 = & S_{ab} S_{cd} A_{ef} \left[K_{am}^0 (2R_{ecb;df}^m - 3/2 R_{nfe}^m R_{cdb}^n - R_{nfd}^m R_{ceb}^n - R_{bnc}^m R_{efd}^n \right. \\
 & + R_{nfb}^m R_{dec}^n + R_{cnd}^m R_{efb}^n - 4R_{nfd}^m R_{ecb}^n - 2R_{ndb}^m R_{efc}^n + R_{fnd}^m R_{ceb}^n \\
 & + R_{fnd}^m R_{ecb}^n - R_{fnb}^m R_{dec}^n) + K_{cm}^0 (R_{bea;df}^m - R_{dea;bf}^m - R_{eda;bf}^m \\
 & + R_{nfe}^m R_{bda}^n + R_{nfd}^m R_{bea}^n - R_{anb}^m R_{efd}^n - R_{nfb}^m R_{dea}^n + R_{and}^m R_{efb}^n \\
 & + 2R_{nfb}^m R_{eda}^n + 2R_{ndb}^m R_{efa}^n - R_{fnd}^m R_{bea}^n + R_{fnb}^m R_{dea}^n + 4R_{fnb}^m R_{eda}^n \\
 & + 3R_{ دنب}^m R_{efa}^n) + K_{em}^0 (R_{bca;df}^m - R_{cda;bf}^m + R_{nfd}^m R_{bca}^n - R_{nfb}^m R_{cda}^n \\
 & - 3R_{ndb}^m R_{fca}^n - R_{fnd}^m R_{bca}^n + R_{fnb}^m R_{cda}^n - 3R_{ دنب}^m R_{fca}^n) - K_{abm}^1 R_{dec;f}^m \\
 & + 2K_{acm}^1 R_{deb;f}^m + 2K_{acm}^1 R_{edb;f}^m + 2K_{aem}^1 R_{cdb;f}^m + 6K_{amc}^1 R_{edb;f}^m \\
 & + 2K_{ame}^1 R_{cdb;f}^m - 2K_{ame}^1 R_{fcb;d}^m - K_{cdm}^1 R_{bea;f}^m - 2K_{cem}^1 R_{bda;f}^m \\
 & - K_{cme}^1 R_{bda;f}^m - K_{cme}^1 R_{bfa;d}^m + K_{cme}^1 R_{dfa;b}^m + K_{cme}^1 R_{fda;b}^m \\
 & + K_{emf}^1 R_{bca;d}^m - K_{emf}^1 R_{cda;b}^m + 3K_{abcm}^2 R_{efd}^m + K_{abem}^2 R_{dfc}^m \\
 & - 6K_{acdm}^2 R_{efb}^m - 2K_{acem}^2 R_{dfb}^m + 4K_{acem}^2 R_{fdb}^m + 6K_{aecm}^2 R_{fdb}^m \\
 & \left. + 2K_{aefm}^2 R_{cdb}^m + K_{cdem}^2 R_{bfa}^m - 2K_{cefm}^2 R_{bda}^m \right]
 \end{aligned}$$

Algebraic superintegrability conditions

- Starting with

$$K_{ij,k} = \frac{1}{3} \begin{array}{|c|c|} \hline j & i \\ \hline k & \\ \hline \end{array} T^m_{ji} K_{mk}$$

- differentiating twice gives

$$\begin{array}{|c|c|} \hline i & j \\ \hline \end{array} R^m_{ikl} g_j^n K_{mn} = \frac{k}{l} \left(P_{ijk}{}^{mn}{}_{,l} + P_{ijk}{}^{pq} P_{pql}{}^{mn} \right) K_{mn}.$$

with $P_{ijk}{}^{mn}$ defined by $K_{ij,k} = P_{ijk}{}^{mn} K_{mn}$

- Now assume an abundance³ of Killing tensors allows K_{mn} to be eliminated

$$\begin{array}{|c|c|} \hline i & j \\ \hline \end{array} R^m_{ikl} g_j^n = \frac{k}{l} \left(P_{ijk}{}^{mn}{}_{,l} + P_{ijk}{}^{pq} P_{pql}{}^{mn} \right).$$

This gives purely algebraic equations in T .

³ $n(n+1)/2$

What now?

- Contracting

$$K_{ij,k} = \frac{1}{3} \begin{array}{|c|c|} \hline j & i \\ \hline k & \\ \hline \end{array} T^m_{ji} K_{mk}$$

gives a linear system for T

$$\lambda_{,i} = -\frac{2}{3}(T_{ijk} - g_{ij}t_k)K^{jk}, \quad \lambda = g_{jk}K^{jk}$$

- This can be solved when

$$D = \det(\mathbf{K}_{11}, \dots, \mathbf{K}_{jk}, \dots, \mathbf{K}_{nn}), \quad 1 \leq j \leq k \leq n,$$

is non-vanishing.

- Known examples suggest D will factor into linear factors as it did in 2 dimensions.
- Conjecture: non-degenerate 2nd order superintegrable systems can be classified by hyperplanes arrangements.